7Vdc -14Vdc input; 0.4Vdc to1.5Vdc output; 120A Output Current

Features

- Compliant to RoHS EU Directive 2002/95/EC (Z versions)
- Compliant to IPC-9592 (September 2008), Category 2
- Compatible in a Pb-free or SnPb reflow environment (Z versions)
- Wide Input voltage range (7Vdc-14 Vdc)
- Output voltage programmable from 0.4Vdc to 1.5Vdc via external resistor or PMBus^{™#} commands
- Digital interface through the PMBus protocol
- Ability to parallel multiple modules (optional)
- Digital sequencing
- Fast digital loop control
- Power Good signal
- Fixed switching frequency with capability of external synchronization
- Output overcurrent protection (non-latching)
- Output overvoltage protection
- Over temperature protection
- Remote On/Off
- Ability to sink and source current
- Cost efficient open frame design
- Small size: 53.8 × 31.7 × 13.3 mm [2.118" × 1.248" × 0.524"]
- Wide operating temperature range [-40°C to 85°C]
- UL* 60950-1 2nd Ed. Recognized, CSA[†] C22.2 No.
 60950-1-07 Certified, and VDE[‡] (EN60950-1 2nd Ed.) Licensed
- ISO** 9001 and ISO 14001 certified manufacturing facilities

Description

Applications

Networking equipment

Industrial equipment

Telecommunications equipment

Servers and storage applications

Distributed power architectures

Intermediate bus voltage applications

The 120A Digital TeraDLynx[™] power modules are non-isolated dc-dc converters that can deliver up to 120A of output current. These modules operate over a 7 to 14Vdc input range and provide a precisely regulated output voltage from 0.4 to 1.5Vdc. The output voltage is programmable via an external resistor and/or PMBus control. Features include a digital interface using the PMBus protocol, remote On/Off, adjustable output voltage, Power Good signal and overcurrent, overvoltage and overtemperature protection. The PMBus interface supports a range of commands to both control and monitor the module. The module also includes a real time compensation loop that allows optimizing the dynamic response of the converter to match the load with reduced amount of output capacitance leading to savings on cost and PWB area.

- * UL is a registered trademark of Underwriters Laboratories, Inc.
- [†] CSA is a registered trademark of Canadian Standards Association.
- [‡] VDE is a trademark of Verband Deutscher Elektrotechniker e.V. ** ISO is a registered trademark of the International Organization of Standards
- # The PMBus name and logo are registered trademarks of the System Management Interface Forum (SMIF)







120A TeraDLynx[™]: Non-Isolated DC-DC Power Modules

7Vdc –14Vdc input; 0.4Vdc to 1.5Vdc output; 120A Output Current

Absolute Maximum Ratings

Stresses in excess of the absolute maximum ratings can cause permanent damage to the device. These are only absolute stress ratings, functional operation of the device is not implied at these or any other conditions in excess of those given in the operations sections of the technical requirements. Exposure to absolute maximum ratings for extended periods can adversely affect the device reliability.

Parameter	Device	Symbol	Min	Max	Unit
Input Voltage - Continuous	All	VIN	-0.3	15	V
SEQ, ADDR0, ADDR1, RTUNE, RTRIM, SYNC, VS+, ON/OFF	All		-0.3	3.6	V
CLK, DATA, SMBALERT#	All		-0.3	3.6	V
Operating Ambient Temperature	All	T _A	-40	85	°C
(see Thermal Considerations section)					
Storage Temperature	All	T _{stg}	-55	125	°C

Electrical Specifications

Unless otherwise indicated, specifications apply over all operating input voltage, resistive load, and temperature conditions.

Parameter	Device	Symbol	Min	Тур	Max	Unit
Operating Input Voltage	All	V _{IN}	7		14	Vdc
Maximum Input Current	All	l _{IN,max}			29	Adc
(V _{IN} =7V to 14V, I _O =I _{O, max})						
Input No Load Current	$V_{O,set} = 0.6 \text{ Vdc}$	I _{IN,No load}		160		mA
$(V_{IN} = 12Vdc, I_0 = 0, module enabled)$	V _{O,set} = 1.5Vdc	I _{IN1No load}		200		mA
Input Stand-by Current (V _{IN} = 12Vdc, module disabled)	All	I _{IN,stand-by}		62		mA
Inrush Transient	All	l²t		1		A ² s
Input Reflected Ripple Current, peak-to-peak (5Hz to 20MHz, 1μH source impedance; V _{IN} =0 to 14V, Io= Iomax; See Test Configurations)	All			5		mAp-p
Input Ripple Rejection (120Hz)	All			-54		dB

7Vdc –14Vdc input; 0.4Vdc to 1.5Vdc output; 120A Output Current

Electrical Specifications (continued)

Parameter	Device	Symbol	Min	Тур	Мах	Unit
Output Voltage Set-point (with 0.1% tolerance external resistor used to set output voltage). Tolerances apply over output voltage range from 0.5 to 1.5V						
-40 to 85°C	All	V _{O, set}	-1.0		+1.0	% V _{O, set}
0 to 85°C	All		-0.7		+0.7	% V _{O, set}
Output Voltage (Over all operating input voltage, resistive load, and temperature conditions until end of life)	All	V _{o, set}	-2.0		+2.0	% V _{O, set}
Adjustment Range (selected by an external resistor)	All	Vout	0.4		1.5	Vdc
PMBus Adjustable Output Voltage Range	All	Vout	0.4		1.5	%V _{0,set}
PMBus Output Voltage Adjustment Step Size	All			98		μV
Remote Sense Range	All				0.3	Vdc
Output Regulation						
Line (V _{IN} =V _{IN, min} to V _{IN, max})	All				5	mV
Load (Io=Io, min to Io, max)	All				5	mV
Temperature ($T_{ref}=T_{A, min}$ to $T_{A, max}$)	All				5	mV
Output Ripple and Noise on nominal output ($V_{IN}=V_{IN, nom}$ and $I_0=I_{0, min}$ to $I_{0, max}$ Co = 1500 μ F						
Peak-to-Peak (Full bandwidth)					30	mV_{pk-pk}
RMS (Full bandwidth)	All				12	mV _{rms}
External Capacitance						
Minimum output capacitance	All	C _{O,min}	1500		—	μF
Maximum output capacitance	All	Co, max	_		40000	μF
Output Current (in either sink or source mode)	All	lo	0.005*		120	Adc
Output Current Limit Inception (Hiccup Mode) (current limit does not operate in sink mode)	All	I _{O, lim}		110		% l _{o,max}
Output Short-Circuit Current	All	I _{01, s/c} , I _{01, s/c}		40		Arms
(V₀≤250mV) (Hiccup Mode)						
Efficiency	V _{0,set} = 0.6Vdc	η		88.2		%
	V _{O, set} = 0.8Vdc	η		90.9		%
V _{IN} = 12Vdc, T _A =25°C	V _{0,set} = 1.0Vdc	η		92.1		%
I_O=I_O, max, V_O= V_O,set	V _{O,set} = 1.2Vdc	η		93.0		%
	V _{O, set} = 1.5Vdc	η		94.0		%
Switching Frequency	All	f _{sw}	-	400	-	kHz
Frequency Synchronization	All					
Synchronization Frequency Range	All		-15		+15	%
High-Level Input Voltage	All	VIH,SYNC	2.5			V
Low-Level Input Voltage	All	VIL,SYNC			1.1	V
Minimum Pulse Width, SYNC	All	t _{sync}	256		1	ns

* Minimum load on module should be 5mA

120A TeraDLynx[™]: Non-Isolated DC-DC Power Modules

7Vdc –14Vdc input; 0.4Vdc to 1.5Vdc output; 120A Output Current

General Specifications

GE

Parameter	Device	Min	Тур	Max	Unit
Calculated MTBF (I_0=0.8I_0, _max, T_A=40 °C) Telecordia Issue 2 Method 1 Case 3	All		11,556,226		Hours
Weight - Module with SMT Pins			57 (2.01)		g (oz.)
Module with Through Hole Pins			59 (2.08)		g (oz.)

Feature Specifications

Unless otherwise indicated, specifications apply over all operating input voltage, resistive load, and temperature conditions. See Feature Descriptions for additional information.

Parameter	Device	Symbol	Min	Тур	Max	Unit
On/Off Signal Interface						
(V_IN=V_IN, min to V_IN, max; open collector or equivalent,						
Signal referenced to GND)						
Device Code with no suffix - Negative Logic (See Ordering Information)						
(On/OFF pin is open collector/drain logic input with						
external pull-up resistor; signal referenced to GND)						
Logic High (Module OFF)						
Input High Current	All	Ін	_	-	1	mA
Input High Voltage	All	VIH	2	-	V _{IN, max}	Vdc
Logic Low (Module ON)						
Input low Current	All	liL	_	-	10	μA
Input Low Voltage	All	VIL	-0.2	-	0.4	Vdc
Device Code with suffix "4" - Positive Logic (See Ordering Information)						
(On/OFF pin is open collector/drain logic input with						
external pull-up resistor; signal referenced to GND)						
Logic High (Module ON)						
Input High Current	All	Ін	_	_	10	μA
Input High Voltage	All	VIH	2	_	V _{IN, max}	Vdc
Logic Low (Module OFF)						
Input low Current	All	lı∟	-	_	10	μA
Input Low Voltage	All	VIL	-0.2	-	0.4	Vdc
Turn-On Delay and Rise Times						
(V_IN=V_{IN, nom, } l_0=l_{0, max,} V_0 to within ±1% of steady state)						
Case 1: On/Off input is enabled and then input power is applied (delay from instant at which $V_{IN} = V_{IN,min}$ until $V_0 = 10\%$ of $V_{0,set}$)	All	Tdelay	_	10	_	ms
Case 2: Input power is applied for at least one second and then the On/Off input is enabled (delay from instant at which Von/Off is enabled until $V_0 = 10\%$ of $V_{0, set}$)	All	Tdelay	_	2	_	ms
Output voltage Rise time (time for V $_{0}$ to rise from 10% of Vo, set to 90% of Vo, set)	All	Trise	_	5	_	msec
Output voltage overshoot ($T_A = 25^{\circ}C$ $V_{IN} = V_{IN, min}$ to $V_{IN, max}$, $I_0 = I_{0, min}$ to $I_{0, max}$) With or without maximum external capacitance		Output			3.0	% V _{O, set}
Over Temperature Protection (See Thermal Considerations section)	All	T _{ref}		135		°C
PMBus Over Temperature Warning Threshold	All	Twarn		125		°C

7Vdc –14Vdc input; 0.4Vdc to 1.5Vdc output; 120A Output Current

Feature Specifications (cont.)

GE

Parameter		Device	Symbol	Min	Тур	Max	Units
Tracking Accuracy	(Power-Up: 0.5V/ms)	All	Vseq –Vo			100	mV
	(Power-Down: 0.5V/ms)	All	Vseq –Vo			100	mV
(VIN, min to VIN, max; IO, min to							
Input Undervoltage Loc	kout						
Turn-on Threshold		All				7	Vdc
Turn-off Threshold				6.75			Vdc
Hysteresis					0.25		Vdc
PMBus Adjustable Input Under Voltage Lockout Thresholds				7		14	Vdc
Resolution of Adjusta	ble Input Under Voltage Threshold	All				5.8	mV
PGOOD (Power Good)							
Signal Interface Ope	n Drain, $V_{supply} \leq 5VDC$						
Overvoltage thresho	ld for PGOOD ON	All			110		$%V_{O, set}$
Overvoltage thresho	ld for PGOOD OFF	All			110		%V _{O, set}
Undervoltage threshold for PGOOD ON		All			90		%V _{O, set}
Undervoltage threshold for PGOOD OFF		All			90		%V _{O, set}
Pulldown resistance of PGOOD pin						2	Ω
Sink current capabili	ty into PGOOD pin	All				50	mA

120A TeraDLynxTM: Non-Isolated DC-DC Power Modules

8Vdc –14Vdc input; 0.4Vdc to 1.5Vdc output; 120A Output Current

Digital Interface Specifications

Unless otherwise indicated, specifications apply over all operating input voltage, resistive load, and temperature conditions. See Feature Descriptions for additional information.

Parameter	Conditions	Symbol	Min	Тур	Max	Unit
PMBus Signal Interface Characteristics						
Input High Voltage (CLK, DATA)		Vih	2.1			V
Input Low Voltage (CLK, DATA)		VIL			1.1	V
Input high level current (CLK, DATA)		Ін			0.5	μA
Input low level current (CLK, DATA)		lıL			4	mA
Output Low Voltage (CLK, DATA, SMBALERT#)	I _{OUT} =4mA	Vol			0.25	V
Output high level open drain leakage current (DATA, SMBALERT#)	V _{OUT} =3.6V	Іон	5		55	nA
Pin capacitance		Co			10	pF
PMBus Operating frequency range	Slave Mode	Fрмв	10		1000	kHz
Data hold time		thd:dat		0		ns
Data setup time		tsu:dat		100		ns
Measurement System Characteristics						·
Read delay time		tdly		110		μs
Output current measurement range		I _{RNG}	0		135	Α
Output current measurement resolution		Ires		250		mA
Output current measurement accuracy	-40°C to +85°C	I _{ACC}			±5	% of Io,max
V _{OUT} measurement range		Vout	0		2.0	V
V _{out} measurement accuracy		V _{OUT(gain)}		±1		% of Vo,max
V _{OUT} measurement resolution		V _{OUT(res)}		0.61		mV
V _{IN} measurement range		VIN	0		16	V
V _{IN} measurement accuracy		V _{IN(gain)}		±2		%
V _{IN} measurement resolution		V _{IN(res)}		5.8		mV
Temperature measurement range		TMEAS	-25		150	°C
Temperature measurement accuracy		T _{MEAS} (gain)	-8		8	°C
Temperature measurement resolution		T _{MEAS(res)}		0.08		°C

120A TeraDLynx[™]: Non-Isolated DC-DC Power Modules

7Vdc –14Vdc input; 0.4Vdc to 1.5Vdc output; 120A Output Current

Characteristic Curves

The following figures provide typical characteristics for the 120A Digital TeraDLynx[™] at 0.6Vo and 25°C.





Figure 1. Converter Efficiency versus Output Current.



$$\label{eq:time_time_t} \begin{split} & \text{TIME, t (50 } \mu \text{s/div)} \\ & \text{Figure 3. Typical output ripple and noise (C_0=12 \times 47 \mu \text{F} \\ & \text{ceramic + 10} \times 470 \mu \text{F polymer, V} \text{In} = 12 \text{V, Io} = \text{Io,max,)}. \end{split}$$



TIME, t (10ms/div)



Figure 2. Derating Output Current versus Ambient Temperature and Airflow.





Figure 4. Transient Response to Dynamic Load Change from 25% to 75% at 12Vin, Co= 12 x 47 μ F + 10 x 1000 μ F, R_{TUNE} = 3.01k Ω .



TIME, t (10ms/div)

Figure 6. Typical Start-up Using Input Voltage ($V_{IN} = 12V$, $I_0 = I_{0,max}$).

7Vdc -14Vdc input; 0.4Vdc to 1.5Vdc output; 120A Output Current

Characteristic Curves

The following figures provide typical characteristics for the 120A TeraDLynx[™] at 0.8Vo and 25°C





Figure 7. Converter Efficiency versus Output Current.



Figure 8. Derating Output Current versus Ambient Temperature and Airflow.



$$\label{eq:time_time_time} \begin{split} & \text{TIME, t (50 } \mu \text{s/div)} \\ & \text{Figure 9. Typical output ripple and noise (} C_0 = 12 \times 47 \mu \text{F} \\ & \text{ceramic + 10} \times 470 \mu \text{F polymer, V} \text{In} = 12 \text{V, Io} = \text{Io}, \text{max.)} \end{split}$$





TIME, t (200µs /div)

Figure 10. Transient Response to Dynamic Load Change from 25% to 75% at 12Vin, Co= 12 x 47µF + 10 x 1000µF, R_{TUNE} = $3.01k\Omega$.



TIME, t (10ms/div)



120A TeraDLynx[™]: Non-Isolated DC-DC Power Modules

7Vdc –14Vdc input; 0.4Vdc to 1.5Vdc output; 120A Output Current

Characteristic Curves

The following figures provide typical characteristics for the 120A Digital TeraDLynx[™] at 1.0Vo and 25°C.





Figure 13. Converter Efficiency versus Output Current.



 $\label{eq:TIME, t} $$TIME, t (50 \mu s/div)$$Figure 15. Typical output ripple and noise (C_0=12x47 \mu F ceramic + 10x470 \mu F polymer, V_{IN} = 12V, I_0 = I_{0,max},)$$}$



Figure 17. Typical Start-up Using On/Off Voltage ($I_0 = I_{0,max}$).

Figure 14. Derating Output Current versus Ambient Temperature and Airflow.



TIME, t (200µs /div)





TIME, t (10ms/div)

Figure 18. Typical Start-up Using Input Voltage (VIN = 12V, $I_{\rm O}$ = $I_{\rm O,max}$).

7Vdc -14Vdc input; 0.4Vdc to 1.5Vdc output; 120A Output Current

Characteristic Curves

The following figures provide typical characteristics for the 120A Digital TeraDLynx™ at 1.2Vo and 25°C.





Figure 19. Converter Efficiency versus Output Current.





Figure 20. Derating Output Current versus Ambient Temperature and Airflow.



TIME, t (50µs/div)







TIME, t (200µs /div)

Figure 22. Transient Response to Dynamic Load Change from 25% to 75% at 12Vin, Co= 12 x 47µF + 10 x 1000µF, RTUNE = **3.01k**Ω.



TIME, t (10ms/div)

Figure 24. Typical Start-up Using Input Voltage (VIN = 12V, Io = lo,max).

120A TeraDLynx[™]: Non-Isolated DC-DC Power Modules

7Vdc –14Vdc input; 0.4Vdc to 1.5Vdc output; 120A Output Current

Characteristic Curves

The following figures provide typical characteristics for the 120A Digital TeraDLynx[™] at 1.5Vo and 25°C.

OUTPUT CURRENT, Io (A)





Figure 25. Converter Efficiency versus Output Current.



TIME, t (50µs/div)

Figure 27. Typical output ripple and noise ($C_0=12x47\mu F$

ceramic + 10x470µF polymer, VIN = 12V, Io = Io,max,)

Figure 26. Derating Output Current versus Ambient Temperature and Airflow.



TIME, t (200µs /div)





TIME, t (2ms/div)

Figure 29. Typical Start-up Using On/Off Voltage ($I_0 = I_{0,max}$). Figure 30.

TIME, t (2ms/div)

Figure 30. Typical Start-up Using Input Voltage (V $_{\rm IN}$ = 12V, $I_{\rm o}$ = $I_{\rm o,max}$).

ON/OFF VOLTAGE Vow/oFF (V) (5V/div)

OUTPUT VOLTAGE Vo (V) (500mV/div)

120A TeraDLynxTM: Non-Isolated DC-DC Power Modules 7Vdc -14Vdc input; 0.4Vdc to 1.5Vdc output; 120A Output Current

Design Considerations

Input Filtering

GF

The 120A TeraDLynx[™] module should be connected to a low ac-impedance source. A highly inductive source can affect the stability of the module. An input capacitance must be placed directly adjacent to the input pins of the module, to minimize input ripple voltage and ensure module stability.

To minimize input voltage ripple, ceramic capacitors are recommended at the input of the module. Figure 31 shows the input ripple voltage for various output voltages at 120A of load current with 4x470 + 12x22 + 12x4.7 μ F and 2x470 + 6x22 + 12x4.7 μ F input capacitor combinations.



Figure 31. Input ripple voltage for various output voltages with two input capacitor combinations at 120A load. Input voltage is 12V.

Output Filtering

These modules are designed for low output ripple voltage and will meet the maximum output ripple specification with minimum of $12 \times 22 \mu$ F ceramic capacitors at the output of the module. However, additional output filtering may be required by the system designer for a number of reasons. First, there may be a need to further reduce the output ripple and noise of the module. Second, the dynamic response characteristics may need to be customized to a particular load step change.

To reduce the output ripple and improve the dynamic response to a step load change, additional capacitance at the output can be used. Low ESR polymer and ceramic capacitors are recommended to improve the dynamic response of the module. Figure 32 provides output ripple information for capacitance of ~3574uF (47µF (1210 ceramic) × 12 + 10µF (0805 ceramic) + 0.1µF (0402) ×4 + 1000µF (polymer) × 3) at various Vo and a full load current of 120A. For stable operation of the module, limit the capacitance to less than the maximum output capacitance as specified in the electrical specification table. Optimal

performance of the module can be achieved by using the Tunable Loop™ feature described later in this data sheet.



Figure 32. Peak to peak output ripple voltage for various output voltages with external capacitors at the output (120A load). Input voltage is 12V.

Safety Considerations

For safety agency approval the power module must be installed in compliance with the spacing and separation requirements of the end-use safety agency standards, i.e., UL 60950-1 2nd, CSA C22.2 No. 60950-1-07, DIN EN 60950-1:2006 + A11 (VDE0805 Teil 1 + A11):2009-11; EN 60950-1:2006 + A11:2009-03.

For the converter output to be considered meeting the requirements of safety extra-low voltage (SELV), the input must meet SELV requirements. The power module has extra-low voltage (ELV) outputs when all inputs are ELV.

The input to these units is to be provided with a slow-blow fuse. When the input voltage is \leq 8V, the recommendation is to use two 25A Littelfuse 456 series or equivalent fuses in parallel. For input voltages > 8V, a single 40A Littelfuse series 456 or equivalent fuse is recommended.

120A TeraDLynx™: Non-Isolated DC-DC Power Modules

7Vdc -14Vdc input; 0.4Vdc to 1.5Vdc output; 120A Output Current

Analog Feature Descriptions

Remote On/Off

The TeraDLynx 120A module can be turned ON and OFF either by using the ON/OFF pin (Analog interface) or through the PMBus interface (Digital). The module can be configured in a number of ways through the PMBus interface to react to the ON/OFF input:

- Module ON/OFF can controlled only through the analog interface (digital interface ON/OFF commands are ignored)
- Module ON/OFF can controlled only through the PMBus interface (analog interface is ignored)
- Module ON/OFF can be controlled by either the analog or digital interface

The default state of the module (as shipped from the factory) is to be controlled by the analog interface only. If the digital interface is to be enabled, or the module is to be controlled only through the digital interface, this change must be made through the PMBus. These changes can be made and written to non-volatile memory on the module so that it is remembered for subsequent use.

Analog On/Off

The 120A Digital TeraDLynx[™] power modules feature an On/Off pin for remote On/Off operation. With the Negative Logic On/Off option, (see Ordering Information), the module turns OFF during logic High and ON during logic Low. The On/Off signal should be always referenced to ground. Leaving the On/Off pin disconnected will turn the module ON when input voltage is present. With the positive logic on/off option, the module turns ON during logic high and OFF during logic low.

Digital On/Off

Please see the Digital Feature Descriptions section.

Monotonic Start-up and Shutdown

The module has monotonic start-up and shutdown behavior on the output for any combination of rated input voltage, output current and operating temperature range.

Startup into Pre-biased Output

The module will start into a pre biased output on output as long as the pre bias voltage is 0.5V less than the set output voltage.

Analog Output Voltage Programming

The output voltage of the module is programmable to any voltage from 0.4 to 1.5Vdc, as shown in Table 1, by connecting a resistor between the Trim and SIG_GND pins of the module as shown in Fig 33.

Without an external resistor between the Trim pin and SIG_GND pins, the output of the module will be 0.1 Vdc. The value of the trim resistor, R_{Trim} for a desired output voltage, should be selected as shown in Table 1.

The trim resistor is only determined during module initialization and hence cannot be used for dynamic output voltage adjustment



Figure 33. Circuit configuration for programming output voltage using an external resistor.

Table 1

V _{O, set} (V)	Rtrim (Ω)	Vo, set (V)	Rtrim (Ω)	V _{O, set} (V)	Rtrim (Ω)
0.400	665	0.800	1740	1.200	5900
0.420	706	0.820	1820	1.220	6420
0.440	741	0.840	1930	1.240	6980
0.460	787	0.860	2030	1.260	7680
0.480	825	0.880	2130	1.280	8450
0.500	866	0.900	2230	1.300	9420
0.520	909	0.920	2340	1.320	10400
0.540	953	0.940	2460	1.340	11700
0.560	1000	0.960	2610	1.360	13500
0.580	1040	0.980	2710	1.380	15800
0.600	1090	1.000	2870	1.400	18900
0.620	1140	1.020	3050	1.420	23200
0.640	1180	1.040	3240	1.440	29800
0.660	1230	1.060	3480	1.460	40200
0.680	1290	1.080	3700	1.480	60400
0.700	1330	1.100	3920	1.500	115000
0.720	1380	1.120	4220		
0.740	1470	1.140	4530		
0.760	1560	1.160	4990		
0.780	1640	1.180	5360		

Digital Output Voltage Adjustment

Please see the Digital Feature Descriptions section.

Remote Sense

The power module has a differential Remote Sense feature to minimize the effects of distribution losses by regulating the voltage between the sense pins (VS+ and VS-) for the output. The voltage drop between the sense pins and the VOUT and GND pins of the module should not exceed 0.3V.

Digital Output Voltage Margining

Please see the Digital Feature Descriptions section.

120A TeraDLynx™: Non-Isolated DC-DC Power Modules

7Vdc –14Vdc input; 0.4Vdc to 1.5Vdc output; 120A Output Current

Output Voltage Sequencing

The power module includes a sequencing feature, EZ-SEQUENCE that enables users to implement various types of output voltage sequencing in their applications. This is accomplished via an additional sequencing pin. When not using the sequencing feature, leave it unconnected.



Figure 34. Circuit showing connection of the sequencing signal to the SEQ pin.

When the sequencing voltage is applied to the SEQ pin, the output voltage tracks this voltage until the output reaches the set-point voltage. The final value of the sequencing voltage must be set higher than the set-point voltage of the module. The output voltage follows the sequencing voltage on a one-to-one basis. By connecting multiple modules together, multiple modules can track their output voltages to the voltage applied on the SEQ pin.

The module's output can track the SEQ pin signal with slopes of up to 0.5V/msec during power-up or power-down.

To initiate simultaneous shutdown of the modules, the SEQ pin voltage is lowered in a controlled manner. The output voltage of the modules tracks the voltages below their setpoint voltages on a one-to-one basis. A valid input voltage must be maintained until the tracking and output voltages reach ground potential.

Digital Sequencing

The module can support digital sequencing by allowing control of the turn-on delay and rise times as well as turn-off and fall times,

Digital Output Voltage Margining

Please see the Digital Feature Descriptions section.

Overcurrent Protection (OCP)

To provide protection in a fault (output overload) condition, the unit is equipped with internal current-limiting circuitry on output and can endure current limiting continuously. The module overcurrent response is non-latching shutdown with automatic recovery. OCP response time is programmable through manufacturer specific commands. The unit operates normally once the output current is brought back into its specified range.

Digital Adjustable Overcurrent Warning

Please see the Digital Feature Descriptions section.

Overtemperature Protection

To provide protection in a fault condition, the unit is equipped with a thermal shutdown circuit. The unit will shut down if the overtemperature threshold of 135 °C (typ) is exceeded at the thermal reference point T_{ref} . Once the unit goes into thermal shutdown it will then wait to cool before attempting to restart.

Digital Adjustable Overcurrent Warning/Shutdown

Please see the Digital Feature Descriptions section.

Digital Temperature Status via PMBus

Please see the Digital Feature Descriptions section.

Digitally Adjustable Output Over and Under Voltage Protection

Please see the Digital Feature Descriptions section.

Input Undervoltage Lockout

At input voltages below the input undervoltage lockout limit, module operation for the associated output is disabled. The module will begin to operate at an input voltage above the undervoltage lockout turn-on threshold.

Digitally Adjustable Input Undervoltage Lockout

Please see the Digital Feature Descriptions section.

Digitally Adjustable Power Good Thresholds

Please see the Digital Feature Descriptions section.

Synchronization

The module switching frequency is capable of being synchronized to an external signal frequency within a specified range. Synchronization is done by using the external signal applied to the SYNC pin of the module as shown in Fig. 35, with the converter being synchronized by the rising edge of the external signal. The Electrical Specifications table specifies the requirements of the external SYNC signal. If the SYNC pin is not used, the module should free run at the default switching frequency.



Figure 35. External source connections to synchronize switching frequency of the module.

Measuring Output Current, Output Voltage and Input Voltage

Please see the Digital Feature Descriptions section.

Digital Compensator

April 24, 2017

7Vdc –14Vdc input; 0.4Vdc to 1.5Vdc output; 120A Output Current

The TJT120 module uses digital control to regulate the output voltage. As with all POL modules, external capacitors are usually added to the output of the module for two reasons: to reduce output ripple and noise and to reduce output voltage deviations from the steady-state value in the presence of dynamic load current changes. Adding external capacitance however affects the voltage control loop of the module, typically causing the loop to slow down with sluggish response. Larger values of external capacitance could also cause the module to become unstable.

The TJT120 comes with default compensation values programmed into the non-volatile memory of the module. These digital compensation values can be adjusted externally to optimize transient response and also ensure stability for a wide range of external capacitance, as well as with different types of output capacitance. This can be done by two different methods.

- By allowing the user to select among several pre-tuned compensation choices to select the one most suited to the transient response needs of the load. This selection is made via a resistor RTune connected between the RTUNE and SIG_GND pins as shown in Fig. 35. Table 2 shows various pre-tuned compensation combinations recommended for various external capacitor combinations.
- 2. Using PMBus to change compensation parameters in the module.

Note that during initial startup of the module, compensation values that are stored in non-volatile memory are used. If a resistor RTune is connected to the module, then the compensation values are changed to ones that correspond to the value of RTUNE. If RTUNE is open however, no change in compensation values is made. Finally, if the user chooses to do so, they can overwrite the compensation values via PMBus commands.

Recommended values of R_{TUNE} for different output capacitor combinations are given in Table 2. If no RTUNE is used, the default compensation values are used.

The TJT120 pre-tuned compensation can be divided into three different banks (COMP1, COMP2, COMP3) that are available to the user to compensate the control loop for various values and combinations of output capacitance and to obtain reliable and stable performance under different conditions. Each bank consists of 20 different sets of compensation coefficients pre-calculated for different values of output capacitance. The three banks are set up as follows:

 COMP1: Recommended for the case where all of the output capacitance is composed of only ceramic capacitors. The range of external output capacitance is from 1470 μF to a maximum value of 17640 $\mu F)$

- COMP2: For the most commonly used mix of ceramic and polymer type capacitors that have higher output capacitance in a smaller size. The range of output capacitance is from 2564 μ F to a maximum of 30564 uF. This is the combination of output capacitance and compensation that can achieve the best transient response at lowest cost and smallest size. For example, with the maximum output capacitance of 12 x 47 μ F ceramics + 25 x 1000 μ F polymer capacitors, and selecting RTUNE = 5.36k Ω , transient deviation can be as low as 25 mV, for a 50% load step (0 to 85A).
- COMP3: Suitable for a mix of ceramic and higher ESR polymers or electrolytic capacitors, with output capacitance ranging from a minimum of 2204 μ F to a maximum of 30084 μ F.

Selecting R_{TUNE} according to Table 2 will ensure stable operation of the module with sufficient stability margin as well as yield optimal transient response.

In applications with tight output voltage limits in the presence of dynamic current loading, additional output capacitance will be required. Table 3 lists recommended values of R_{TUNE} in order to meet 2% output voltage deviation limits for some common output voltages in the presence of an 60A to 120A step change (50% of full load), with an input voltage of 12V. Please contact your GE technical representative to obtain more details of this feature as well as for guidelines on how to select the right value of external RTUNE to tune the module for best transient performance and stable operation for other output capacitance values. Simulation models are also available via the GE Power Module Wizard to predict stability characteristics and transient response.



Figure 36. Circuit diagram showing connection of R_{TUNE} to tune the control loop of the module.

7Vdc –14Vdc input; 0.4Vdc to 1.5Vdc output; 120A Output Current

Output	Number of Output	Total Output	RTUNE	RTUNE		-		
Capacitance Type	Capacitors**	Capacitance (µF)**	resistor (Ω)	Index	KD	KI	KP	AP
	efault Compensation Value		OPEN		375	2	37	150
Ceramic	10 x 47µF + 10 x 100µF	1398	29.1	0	375	2	37	150
Ceramic	12 x 47µF + 12 x 100µF	1644	88.7	1	441	3	44	150
Ceramic	14 x 47µF + 14 x 100µF	1890	150	2	506	3	51	150
Ceramic	16 x 47µF + 16 x 100µF	2136	213	3	572	3	57	150
Ceramic	19 x 47µF + 19 x 100µF	2505	280	4	671	3	67	150
Ceramic	22 x 47µF + 22 x 100µF	2874	348	5	770	4	77	150
Ceramic	25 x 47µF + 25 x 100µF	3243	417	6	869	4	87	150
Ceramic	28 x 47µF + 28 x 100µF	3612	493	7	968	4	97	150
Ceramic	31 x 47µF + 31 x 100µF	3981	569	8	1067	4	107	150
Ceramic	34 x 47µF + 34 x 100µF	4350	642	9	1166	4	117	150
Ceramic	38 x 47µF + 38 x 100µF	4842	723	10	1297	5	130	150
Ceramic	42 x 47µF + 42 x 100µF	5334	806	11	1429	5	143	150
Ceramic	48 x 47µF + 48 x 100µF	6072	898	12	1627	5	163	150
Ceramic	55 x 47µF + 55 x 100µF	6933	938	13	1858	5	186	150
Ceramic	63 x 47µF + 63 x 100µF	7917	1090	14	2121	6	212	150
Ceramic	72 x 47µF + 72 x 100µF	9024	1180	15	2418	6	242	150
Ceramic	82 x 47µF + 82 x 100µF	10254	1290	16	2748	7	275	150
Ceramic	93 x 47µF + 93 x 100µF	11607	1400	17	3110	7	311	150
Ceramic	105 x 47µF + 105 x 100µF	13083	1520	18	3506	7	351	150
Ceramic	120 x 47µF + 120 x 100µF	14928	1640	19	4000	8	400	150
Ceramic + Polymer	12 x 47µF + 2 x 1000µF	2672	1760	20	501	3	300	220
Ceramic + Polymer	12 x 47µF + 3 x 1000µF	3672	1890	21	688	3	413	220
Ceramic + Polymer	12 x 47µF + 4 x 1000µF	4672	2030	22	876	3	525	220
Ceramic + Polymer	12 x 47µF + 5 x 1000µF	5672	2150	23	1063	4	638	220
Ceramic + Polymer	12 x 47µF + 6 x 1000µF	6672	2320	24	1250	4	750	220
Ceramic + Polymer	12 x 47µF + 7 x 1000µF	7672	2460	25	1438	4	860	220
Ceramic + Polymer	12 x 47µF + 8 x 1000µF	8672	2640	26	1625	5	975	220
Ceramic + Polymer	12 x 47µF + 9 x 1000µF	9672	2840	27	1813	5	1088	220
Ceramic + Polymer	12 x 47μF + 10 x 1000μF	10672	3010	28	2000	5	1200	220
Ceramic + Polymer	12 x 47μF + 11 x 1000μF	11672	3200	29	2187	5	1312	220
Ceramic + Polymer	12 x 47μF + 12 x 1000μF	12672	3400	30	2375	5	1425	220
Ceramic + Polymer	12 x 47µF + 13 x 1000µF	13672	3650	31	2562	6	1537	220
Ceramic + Polymer	12 x 47µF + 15 x 1000µF	15672	3880	32	2937	6	1762	220
Ceramic + Polymer	12 x 47µF + 17 x 1000µF	17672	4120	33	3312	6	1987	220
Ceramic + Polymer	12 x 47µF + 19 x 1000µF	19672	4420	34	3687	7	2212	220
Ceramic + Polymer	12 x 47µF + 21 x 1000µF	21672	4700	35	4061	7	2437	220
Ceramic + Polymer	12 x 47µF + 23 x 1000µF	23672	5050	36	4436	7	2662	220
Ceramic + Polymer	12 x 47μF + 25 x 1000μF	25672	5360	37	4811	8	2887	220
Ceramic + Polymer	12 x 47μF + 27 x 1000μF	27672	5760	38	5186	8	3112	220
Ceramic + Polymer	12 x 47μF + 30 x 1000μF	30672	6120	39	5748	8	3449	220

Table 2. Recommended RTUNE Compensation.

** Total output capacitance includes the capacitance inside the module is 4 x 47µF (3m Ω ESR).

Note: The capacitors used in the digital compensation Loop tables are 47µF/3 m Ω ESR ceramic, 100uF/3.2m Ω ceramic, 1000 µF/6m Ω ESR polymer capacitor and 820uF/19m Ω ESR Polymer capacitor.

7Vdc –14Vdc input; 0.4Vdc to 1.5Vdc output; 120A Output Current

Output Capacitance Type	Number of Output Capacitors**			RTUNE Index	KD	KI	KP	AP				
Ceramic + Electrolytic	12 x 47µF + 2 x 820µF	2312	6570	40	176	2	176	220				
Ceramic + Electrolytic	12 x 47µF + 3 x 820µF	3312	7060	41	238	3	238	220				
Ceramic + Electrolytic	12 x 47µF + 4 x 820µF	3952	7590	42	301	3	301	220				
Ceramic + Electrolytic	12 x 47µF + 5 x 820µF	4772	8160	43	363	3	363	220				
Ceramic + Electrolytic	12 x 47µF + 6 x 820µF	5592	8870	44	426	4	426	220				
Ceramic + Electrolytic	12 x 47µF + 7 x 820µF	6412	9530	45	488	4	488	220				
Ceramic + Electrolytic	12 x 47µF + 8 x 820µF	7312	10400	46	550	4	550	220				
Ceramic + Electrolytic	12 x 47µF + 9 x 820µF	8052	11300	47	613	4	613	220				
Ceramic + Electrolytic	12 x 47µF + 10 x 820µF	8872	12400	48	675	5	675	220				
Ceramic + Electrolytic	12 x 47µF + 11 x 820µF	9692	13700	49	738	5	738	220				
Ceramic + Electrolytic	12 x 47µF + 12 x 820µF	10512	15000	50	800	5	800	220				
Ceramic + Electrolytic	12 x 47µF + 14 x 820µF	12152	16700	51	925	5	925	220				
Ceramic + Electrolytic	12 x 47µF + 16 x 820µF	13792	18700	52	1050	6	1050	220				
Ceramic + Electrolytic	12 x 47µF + 18 x 820µF	15432	21000	53	1174	6	1174	220				
Ceramic + Electrolytic	12 x 47µF + 20 x 820µF	17072	24000	54	1299	6	1299	220				
Ceramic + Electrolytic	12 x 47µF + 23 x 820µF	19532	28000	55	1486	7	1486	220				
Ceramic + Electrolytic	12 x 47µF + 26 x 820µF	21992	33000	56	1674	7	1674	220				
Ceramic + Electrolytic	12 x 47µF + 29 x 820µF	24452	40200	57	1861	8	1861	220				
Ceramic + Electrolytic	12 x 47µF + 32 x 820µF	26912	50500	58	2048	8	2048	220				
Ceramic + Electrolytic	12 x 47µF + 36 x 820µF	30192	68000	59	2298	8	2298	220				

Table 2 (continued). RTUNE compensation table

** Total output capacitance includes the capacitance inside the module is 4 x 47 μ F (3m Ω ESR).

Note: The capacitors used in the digital compensation Loop tables are 47μ F/3 m Ω ESR ceramic, 100μ F/3.2m Ω ceramic, 1000μ F/6m Ω ESR polymer capacitor and 820μ F/19m Ω ESR Electrolytic capacitor.

120A TeraDLynxTM: Non-Isolated DC-DC Power Modules 7Vdc –14Vdc input; 0.4Vdc to 1.5Vdc output; 120A Output Current

Digital Feature Descriptions

PMBus Interface Capability

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The 120A TeraDLynx power modules have a PMBus interface that supports both communication and control. The PMBus Power Management Protocol Specification can be obtained from <u>www.pmbus.org</u>. The modules support a subset of version 1.1 of the specification (see Table 4 for a list of the specific commands supported). Most module parameters can be programmed using PMBus and stored as defaults for later use.

Communication over the module PMBus interface supports the Packet Error Checking (PEC) scheme. The PMBus master must generate the correct PEC byte for all transactions, and check the PEC byte returned by the module.

The module also supports the SMBALERT# response protocol whereby the module can alert the bus master if it wants to talk. For more information on the SMBus alert response protocol, see the System Management Bus (SMBus) specification.

The module has non-volatile memory that is used to store configuration settings. Not all settings programmed into the device are automatically saved into this non-volatile memory, only those specifically identified as capable of being stored can be saved (see Table 4 for which command parameters can be saved to non-volatile storage).

PMBus Data Format

For commands that set thresholds, voltages or report such quantities, the module supports the "Linear" data format among the three data formats supported by PMBus. The Linear Data Format is a two-byte value with an 11-bit, two's complement mantissa and a 5-bit, two's complement exponent. The format of the two data bytes is shown below:



The value is of the number is then given by

Value = Mantissa x 2 ^{Exponent}

PMBus Addressing

The power module is addressed through the PMBus using a device address. The module supports 128 possible addresses (0 to 127 in decimal) which can be set using resistors connected from the ADDR0 and ADDR1 pins to SIG_GND. Note that some of these addresses (0, 1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 11 12, 40, 44, 45, 55 in decimal) are reserved according to the SMBus specification and may not be useable. The address is set in the form of two octal (0 to 7) digits, with each pin setting one digit. The ADDR1 pin sets the high order digit and ADDR0 sets the low order digit. The resistor values suggested for each digit are shown in Table 3 (E96 series resistors are recommended). Note that if either address resistor value is outside the range specified in Table 4, the module will respond to address 127.

The user must know which I²C addresses are reserved in a system for special functions and set the address of the module to avoid interfering with other system operations. Both 100kHz and 400kHz bus speeds are supported by the module. Connection for the PMBus interface should follow the High Power DC specifications given in section 3.1.3 in the SMBus specification V2.0 for the 400kHz bus speed or the

Low Power DC specifications in section 3.1.2. The complete SMBus specification is available from the SMBus web site, <u>smbus.org</u>.



Figure 37. Circuit showing connection of resistors used to set the PMBus address of the module.

					able 3	Table								
	PMBus Address Table ADDR1 Resistor Values													
ADDR0 Resistor Values	4.99K	15.4k	27.4K	41.2K	54.9K	71.5K	90.9K	110K	137K	162K	191K			
4.99K	1	13	25	37	49	61	73	85	97	109	121			
15.4K	2	14	26	38	50	62	74	86	98	110	122			
27.4K	3	15	27	39	51	63	75	87	99	111	123			
41.2K	4	16	28	40	52	64	76	88	100	112	124			
54.9K	5	17	29	41	53	65	77	89	101	113	125			
71.5K	6	18	30	42	54	66	78	90	102	114	126			
90.9K	7	19	31	43	55	67	79	91	103	115	127			
110K	8	20	32	44	56	68	80	92	104	116	64			
137K	9	21	33	45	57	69	81	93	105	117	64			
162K	10	22	34	46	58	70	82	94	106	118	64			
191K	11	23	35	47	59	71	83	95	107	119	64			
232K	12	24	36	48	60	72	84	96	108	120	64			

7Vdc –14Vdc input; 0.4Vdc to 1.5Vdc output; 120A Output Current

Operation (01h)

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This is a paged register. The OPERATION command can be used to turn the module on or off in conjunction with the ON/OFF pin input. It is also used to margin up or margin down the output voltage

PMBus Enabled On/Off

The module can also be turned on and off via the PMBus interface. The OPERATION command is used to actually turn the module on and off via the PMBus, while the ON_OFF_CONFIG command configures the combination of analog ON/OFF pin input and PMBus commands needed to turn the module on and off. Bit [7] in the OPERATION command data byte enables the module, with the following functions:

- 0 : Output is disabled
- 1 : Output is enabled

This module uses the lower five bits of the ON_OFF_CONFIG data byte to set various ON/OFF options as follows:

Bit Position	4	3	2	1	0
Access	r/w	r/w	r/w	r	r
Function	PU	CMD	CPR	POL	CPA
Default Value	1	0	1	x	1

PU: Sets the default to either operate any time input power is present or for the ON/OFF to be controlled by the analog ON/OFF input and the PMBus OPERATION command. This bit is used together with the CP, CMD and ON bits to determine startup.

Bit Value	Action
0	Module powers up any time power is present regardless of state of the analog ON/OFF pin
1	Module does not power up until commanded by the analog ON/OFF pin and the OPERATION command as programmed in bits [2:0] of the ON_OFF_CONFIG register.

CMD: The CMD bit controls how the device responds to the OPERATION command.

Bit Value	Action
0	Module ignores the ON bit in the OPERATION command
1	Module responds to the ON bit in the OPERATION command

CPR: Sets the response of the analog ON/OFF pin. This bit is used together with the CMD, PU and ON bits to determine startup.

Bit Value	Action	
0	Module ignores the analog ON/OFF pin, i.e. ON/OFF is only controlled through the PMBUS via the OPERATION command	
1	Module requires the analog ON/OFF pin to be asserted to start the unit	

CPA: Sets the action of the analog ON/OFF pin when turning the controller OFF. This bit is internally read and cannot be modified by the user

PMBus Adjustable Soft Start Rise Time

The soft start rise time of module output is adjustable in the module via PMBus. The TON_RISE command can set the rise time in ms, and allows choosing soft start times between 0 and 1000ms. While this is the settable range, the actual rise time should be set considering the charging current of the output capacitors and starting current required by the load. Setting the TON_RISE too low could trigger the overcurrent protection. The default setting for TON_RISE is 5msec.

Output Voltage Adjustment Using the PMBus

Two PMBus commands are available to change the output voltage setting. The first, VOUT_COMMAND can set the output voltage directly. The second, VOUT_TRIM is used to apply an offset to the commanded output voltage.

Since the output voltage can be set using an external RTrim resistor as well, an additional PMBus command MFR_VOUT_SET_MODE is used to tell the module whether the VOUT_COMMAND is used to directly set output voltage or whether RTrim is to be used. If MFR_VOUT_SET_MODE is set to where bit position 7 is set at 1, then VOUT_COMMAND is ignored and output voltage is set solely by RTrim. If bit 7 of MFR_VOUT_SET_MODE is set to 0, then output voltage is set using VOUT_COMMAND, and the value of RTrim is only used at startup to set the output voltage.

The second output voltage adjustment command VOUT_TRIM works in either case to provide a fixed offset to the output voltage. This allows PMBus adjustment of the output voltage irrespective of how MFR_VOUT_SET_MODE is set and allows digital adjustment of the output voltage setting even when RTrim is used.

For all digital commands used to set or adjust the output voltage via PMBus, the resolution is 98μ V.

Output Voltage Margining Using the PMBus

The output voltage of the module can be margined via PMBus between 0.4 and 1.5V. The margining voltage can be adjusted in 98μ V steps.

PMBus Adjustable Overcurrent Warning

The module can provide an overcurrent warning via the PMBus. The threshold for the overcurrent warning can be set using the parameter IOUT_OC_WARN_LIMIT. This command uses the "Linear" data format with a two byte data word where the upper five bits [7:3] of the high byte represent the exponent and the remaining three bits of the high byte [2:0] and the eight bits in the low byte represent the mantissa. The value of the IOUT_OC_WARN_LIMIT can be stored to non-volatile memory using the STORE_DEFAULT_ALL command.

Temperature Status via PMBus

The module provides information related to temperature of the module through standardized PMBus commands. Commands READ_TEMPERATURE1, READ_TEMPERATURE_2 are mapped to module temperature and internal

120A TeraDLynx™: Non-Isolated DC-DC Power Modules

7Vdc –14Vdc input; 0.4Vdc to 1.5Vdc output; 120A Output Current

temperature of the PWM controller, respectively. The temperature readings are returned in °C and in two bytes.

PMBus Adjustable Output Over, Under Voltage Protection

The module has output over and under voltage protection capability. The PMBus command VOUT_OV_FAULT_LIMIT is used to set the output over voltage threshold. The default value is configured to be 112.5% of the commanded output. The command VOUT_UV_FAULT_LIMIT sets the threshold that detects an output under voltage fault. The default values are 87.5% of the commanded output voltage. Both commands use two data bytes formatted in the Linear format.

PMBus Adjustable Input Undervoltage Lockout

The module allows adjustment of the input under voltage lockout and hysteresis. The command VIN_ON allows setting the input voltage turn on threshold, while the VIN_OFF command sets the input voltage turn off threshold. For the VIN_ON command possible values are 7 to 14V and for the VIN_OFF command, possible values are 6.75V to 14V. Both VIN_ON and VIN_OFF commands use the "Linear" format with two data bytes.

Measurement of Output Current, Output Voltage and Input Voltage

The module can measure key module parameters such as output current, output voltage and input voltage and provide this information through the PMBus interface.

Measuring Output Current Using the PMBus

The module measures output current by using a signal derived from the switching FET currents. The current gain factor is accessed using the IOUT_CAL_GAIN command, and consists of two bytes in the Linear data format. During manufacture, each module is calibrated by measuring and storing the current gain factor into non-volatile storage.

The current measurement accuracy is also improved by each module being calibrated during manufacture with the offset in the current reading. The IOUT_CAL_OFFSET command is used to store and read the current offset. The READ_IOUT command provides module average output current information. This command only supports positive output current, i.e. current sourced from the module. If the converter is sinking current a reading of 0 is provided. The READ_IOUT command returns two bytes of data in the Linear data format.

Measuring Output Voltage Using the PMBus

The module provides output voltage information using the READ_VOUT command. The command returns two bytes of data in Linear format.

Measuring Input Voltage Using the PMBus

The module provides input voltage information using the READ_VIN command. The command returns two bytes of data in the Linear format.

Reading the Status of the Module using the PMBus

The module supports a number of status information commands implemented in PMBus. A 1 in the bit position indicates the fault that is flagged.

STATUS_BYTE: Returns one byte of information with a summary of the most critical device faults.

Bit Position	Flag	Default Value
7	X	0
6	OFF	0
5	VOUT Overvoltage	0
4	IOUT Overcurrent	0
3	VIN Undervoltage	0
2	Temperature	0
1	CML (Comm. Memory Fault)	0
0	None of the above	0

STATUS_WORD: Returns two bytes of information with a summary of the module's fault/warning conditions.

Bit Position	Flag	Default Value
7	Х	0
6	OFF	0
5	VOUT Overvoltage	0
4	IOUT Overcurrent	0
3	VIN Undervoltage	0
2	Temperature	0
1	CML (Comm. Memory Fault)	0
0	None of the above	0

High Byte

Bit Position	Flag	Default Value
7	VOUT fault or warning	0
6	IOUT fault or warning	0
5	Х	0
4	Х	0
3	POWER_GOOD# (is negated)	0
2	X	0
1	X	0
0	X	0

STATUS_VOUT: Returns one byte of information relating to the status of the module's output voltage related faults.

Bit Position	Flag	Default Value
7	VOUT OV Fault	0
6	VOUT_OV_WARNING	0
5	VOUT_UV_WARNING	0
4	VOUT UV Fault	0
3	×	0
2	X	0
1	X	0
0	Х	0

120A TeraDLynx™: Non-Isolated DC-DC Power Modules

7Vdc –14Vdc input; 0.4Vdc to 1.5Vdc output; 120A Output Current

STATUS_IOUT: Returns one byte of information relating to the status of the module's output voltage related faults.

Bit Position	Flag	Default Value
7	IOUT OC Fault	0
6	×	0
5	IOUT OC Warning	0
4	×	0
3	×	0
2	×	0
1	X	0
0	X	0

STATUS_TEMPERATURE: Returns one byte of information relating to the status of the module's temperature related faults.

Bit Position	Flag	Default Value
7	OT Fault	0
6	OT Warning	0
5	Х	0
4	X	0
3	Х	0
2	×	0
1	X	0
0	×	0

STATUS_CML: Returns one byte of information relating to the status of the module's communication related faults.

Bit Position	Flag	Default Value
7	Invalid/Unsupported Command	0
6	Invalid/Unsupported Data	0
5	Packet Error Check Failed	0
4	Memory Fault Detected	0
3	Х	0
2	X	0
1	Other Communication Fault	0
0	X	0

MFR_SPECIFIC_00: Returns information related to the type of module and revision number. Bits [7:2] in the Low Byte indicate the module type (001101 corresponds to the TJT120 series of module), while bits [7:3] in the high byte indicate the revision number of the module.

Low Byte		
Bit Position	Flag	Default Value
7:2	Module Name	001101
1:0	Reserved	10

High Byte		
Bit Position	Flag	Default Value
7:3	Module Revision Number	None
2:0	Reserved	000

User-Programmable Compensation Coefficients

The output voltage control compensation coefficients can be changed by the user via PMBus commands. On startup, the module uses stored values of the four compensation parameters KD, KI, KP and ALPHA. If the module detects a valid value of RTUNE connected to the module, the values of KD, KI, KP and ALPHA are then changed to the appropriate values. Beyond this, the user can use the PMBus commands listed below to overwrite the values of KD, KP, KI and ALPHA.

MFR_SPECIFIC_KP: Allows the user to program the value of the KP compensation coefficient. The allowed range is -32768 to 32767. The entire 16 bits are used to enter this range of integer values in two's complement binary format.

MFR_SPECIFIC_KI: Allows the user to program the value of the KI compensation coefficient. The allowed range is -32768 to 32767. The entire 16 bits are used to enter this range of integer values in two's complement binary format.

MFR_SPECIFIC_KD: Allows the user to program the value of the KD compensation coefficient. The allowed range is -32768 to 32767. The entire 16 bits are used to enter this range of integer values in two's complement binary format.

MFR_SPECIFIC_ALPHA: Allows the user to program the value of the ALPHA compensation coefficient. The allowed range is -256 to 256. The entire 16 bits are used to enter this range of integer values in two's complement binary format.

7Vdc –14Vdc input; 0.4Vdc to 1.5Vdc output; 120A Output Current

Summary of Supported PMBus Commands

Please refer to the PMBus 1.1 specification for more details of these commands. For the registers where a range is specified, any value outside the range is ignored and the module continues to use the previous value. **Table 4**

				Tab	le 4							
Hex Code	Command				Brief D	escript	ion					Non-Volatile Memory Storage
		Turn Module on or	off. Also	used to	o margir	n the ou	tput vol	tage				
		Format				Jnsigne	d Binar	v				
01		Bit Position	7	6	5	4	3	2	1	0		1/50
01	OPERATION	Access	r/w	r	r/w	r/w	r/w	r/w	r	r		YES
		Function	On	X	.,		rgin	.,	X	X		
		Default Value	1	0	0	0	0	0	Х	Х		
		Configures the ON/ PMBus commands	OFF fun	ictionali		combine Jnsigne			ON/OF	F pin and	ł	
02	ON OFF CONFIG	Bit Position	7	6	5	4	3	2	1	0		YES
		Access	r	r	r	r/w	r/w	r/w	r	r		
		Function	Х	Х	Х	pu	cmd	cpr	Х	сра		
		Default Value	0	0	0	1	0	1	0	1		
03	CLEAR_FAULTS	Clear any fault bits device has been as	serting	it.						-		
		Used to control wri the module whose memory (EEPROM)	comma	nd code	e match		value in	the dat				
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r/w	r/w	r/w	х	х	×	х	х		
		Function	bit7	bit6	bit5	Х	Х	Х	Х	Х		
10	WRITE PROTECT	Default Value	0	0	0	Х	Х	Х	Х	Х		YES
		1 – Disables all and ON_OF Bit 6: 0 – Enables al 0 – Disables al 0 PERATION Bit7: 0 – Enables all 1 – Disables all (bit5 and bi	 Bit5: 0 – Enables all writes as permitted in bit6 or bit7 1 – Disables all writes except the WRITE_PROTECT, OPERATION and ON_OFF_CONFIG (bit 6 and bit7 must be 0) Bit 6: 0 – Enables all writes as permitted in bit5 or bit7 1 – Disables all writes except for the WRITE_PROTECT and OPERATION commands (bit5 and bit7 must be 0) Bit7: 0 – Enables all writes as permitted in bit5 or bit6 1 – Disables all writes except for the WRITE_PROTECT command 									
11	STORE_DEFAULT_ALL	Copies all current re on the module. Tak	egister s	settings	in the r	nodule i comma	into nor	n-volatil	e memo	ory (EEPR	(OM)	
		Restores all current							n the m	odule no	n-	
12	RESTORE_DEFAULT_ALL	volatile memory (EE		· securi								
		The module has MC changed Bit Position	DDE set	to Linec	ar and E	xponen 4	t set to 3	-14. The	ese valu	ies canno	ot be	
20	VOUT_MODE	Access	r	r	r	r	r	r	r	r		
		Function		Mode			s comp	lement	Expone	ent		
		Default Value	0	0	0	1	0	0	1	0		
	Set desired output voltage. Only 16-bit unsigned mantissa – implied exponent of -14 per VOUT_MODE command. Valid range is 0.4 to 1.5V. Format Unsigned Mantissa Bit Position 15 14 13 12 11 10 9 8 Access r/w r/w r/w r/w r/w r/w r/w r/w											
21	VOUT_COMMAND	Function		·	·		tissa	·				YES
	-	Default Value					able					
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
		Function					tissa					
		Default Value				Vari	able					

7Vdc –14Vdc input; 0.4Vdc to 1.5Vdc output; 120A Output Current

Hex	Command				Brie	ef Desci	ription					Non-Volatile
Code	Command	Angle official official						:+	the DTa		***	Memory Storage
		Apply a fixed offset VOUT_COMMAND.								m resis	tor or the	
		Allowed range is ± 3		capone	11101 1	- per v	501_110		innana.			
		Format			U	nsigned	l Mantis	sa				
		Bit Position	15	14	13	12	11	10	9	8		
22	VOUT TRIM	Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w		YES
22	V001_IIIIII	Function					tissa					TES
		Default Value	0	0	0	0	0	0	0	0		
		Bit Position Access	7 r/w	6 r/w	5 r/w	4 r/w	3 r/w	2 r/w	1 r/w	0 r/w		
		Function	17 VV	17 VV	17 VV		tissa	17 VV	17 VV	1/ VV		
		Default Value	0	0	0	0	0	0	0	0		
-		L		-						-		
		Applies an offset to output voltage (bet	the cor		ea outp and ±10	ut voita I0mV) a	ge to co nd whe	andrate	out erro	rs in se a ic cot v	ing module	
		command VOUT_C										
		Format	-				npleme					
		Bit Position	15	14	13	12	11	10	9	8		
23	VOUT CAL OFFSET	Access	r/w	r	r	r	r	r	r	r		YES
23	VUUI_UAL_UFFSEI	Function					tissa					TEO
		Default Value	_			ased on	factory		tion			
		Bit Position	/	6	5	4	3	2	1	0		
		Access Function	r	r/w	r/w	r/w Man	r/w tissa	r/w	r/w	r/w		
		Default Value		Var	iahle ha		factory	calibra	tion			
							,					
		Sets the target volt						plied ex	ponent	of -14 p	ber	
		VOUT_MODE comn	nana. Ai				5V mpleme	nt hina	n (Ì	
		Bit Position	15	14	13	12	11	10	y 9	8		
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
25	VOUT MARGIN HIGH	Function	.,	.,	.,		tissa	.,	.,	.,		YES
		Default Value					able					
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
		Function					tissa					
		Default Value				Vari	able					
		Sets the target volt VOUT_MODE comn						lied exp	onent c	f -14 pe	er	
		Format					npleme	nt binar	Ŷ			
		Bit Position	15	14	13	12	11	10	9	8		
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
26	VOUT_MARGIN_LOW	Function					tissa					YES
		Default Value	_	-	-		able					
		Bit Position	7	6	5	4	3	2	1	0		
		Access Function	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
		Default Value					tissa able					
			I			vull	UDIC				1	
		Sets the value of in range is 7 to 14V.	put volte	5						s fixed o	at -6. Allowed	
		Format			inear, t		mpleme]	
		Bit Position	15	14	13	12	11	10	9	8		
		Access	r	r	r	r	r	r	r/w	r/w		
35	VIN_ON	Function	1		Exponer		<u> </u>		Mantiss		{	YES
		Default Value Bit Position	1 7	1 6	0 5	1 4	0	0	0	10	{	
		Access	r/w	ь r/w	r/w	r/w	r/w	r/w	r/w	r/w	1	
		Function	17 VV	17 VV	17 VV		itissa	17 VV	17 VV	17 VV	1	
		Default Value	1	1	0	0	0	0	0	0	1	
			-		Ŭ	Ť	Ť	, °	-	,	1	

7Vdc –14Vdc input; 0.4Vdc to 1.5Vdc output; 120A Output Current

Hex Code	Command				Brief	Descrip	otion					Non-Volatile Memory Storage
Coue		Sets the value of in	out volt	aae at v	which th	e modu	la turns	off Ev	oonent i	s fived i	at -6	Plemory Storage
		Allowed range is 6.					ie turns		Jonenti	5 IIAEU I	ut -0.	
		Format			inear, tv	vo's cor	npleme	nt binaı	ſy]	
		Bit Position	15	14	13	12	11	10	9	8		
		Access	r	r	r	r	r	r	r/w	r/w		
36	VIN_OFF	Function			Exponer				Mantisso			YES
		Default Value	1	1	0	1	0	0	0	1		
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
		Function	1		1	Man		0	0	0		
		Default Value	1	0	1	1	0	0	0	0		
		Applies a gain corre										
		module measurem								r is divio	ded by 8192	
		to generate the cor	rection								1	
		Format Bit Desition	10			vo's cor			-	0		
		Bit Position Access	15	14	13	12	11	10	9	8 r/w		
38	IOUT_CAL_GAIN		r	r	r	[Into	r	r	r	r/w		YES
		Function Default Value		Var	iahla ha	Inte used on	5	calibra	tion			
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
		Function	1700	17 00	17 00	Inte		17 00	17 VV	17 00		
		Default Value		Var	iable ba	used on		calibra	tion			
		Returns the value o current. The expone								ured ou	itput	
			ent is tix								1	
		Format Bit Desition	10			vo's cor			-			
		Bit Position	15	14 r	13	12 r	11 r	10 r/w	9 r	8		
70		Access Function	r		r Exponer		1		Mantisso	r		1/50
39	IOUT_CAL_OFFSET	Default Value	1	1	1	1	0		Variable			YES
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r	r	r/w	r/w	r/w	r/w	r/w	r/w		
		Function			.,	Man		1,	17 **	17.00		
		Default Value		Var	iable bo	ased on		calibra	tion			
		Sets the voltage lev						plied ex	ponent	of -14 p	ber	
		VOUT_MODE comm	nand. Al								7	
		Format Bit Desition	10	1		wo's co	<u> </u>	1	<i>í</i>	<u> </u>	4	
		Bit Position	15	14	13	12	11	10	9	8	-	
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w	4	
40	VOUT_OV_FAULT_LIMIT	Function					itissa				4	YES
		Default Value	7	C	г		able	۰ ۱	1	0	-	
		Bit Position Access	7 r/w	6	5	4 r/w	3	2	1	0	-	
		Function	r/w	r/w	r/w		r/w itissa	r/w	r/w	r/w	-	
		Default Value					iable				-	
			<u> </u>									
		Instructs the modul	e on wł	nat actio					utput ov	ervolta	ge fault	
		Format		1		Unsigne	1				4	
		Bit Position	7	6	5	4	3	2	1	0	4	
41	VOUT_OV_FAULT_RESPONSE	Access	r/w	r/w	r/w	r/w	r/w	r	r	r	4	YES
		Function	RSP [1]	RSP [0]	RS[2]	RS[1]	RS[0]	Х	Х	Х		
		Default Value	1	0	1	1	1	0	0	0]	
											-	1

7Vdc –14Vdc input; 0.4Vdc to 1.5Vdc output; 120A Output Current

Hex Code	Command				Brief	Descri	ption					Non-Volatile Memory Storage
		Sets the value of ou	utput vo	ltage at	t which	the mod	dule ger	nerates	warning	g for ove	er-voltage.	
		Exponent is fixed at	t -14. Al									
		Format		L	inear, tv.	<i>w</i> o's cor	npleme	nt binaı	У			
		Bit Position	15	14	13	12	11	10	9	8		
		Access	r	r	r	r	r	r/w	r/w	r/w		
42	VOUT_OV_WARN_LIMIT	Function		E	Exponer	nt		1	Mantisso	a		YES
		Default Value				Vari	able					
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
		Function				Man	tissa					
		Default Value				Vari	able					
		Sets the value of ou						nerates	warning	g for und	der-voltage.	
		Exponent is fixed at	t -14. Al									
		Format			inear, tv							
		Bit Position	15	14	13	12	11	10	9	8		
		Access	r	r	r	r	r	r/w	r/w	r/w		
43	VOUT_UV_WARN_LIMIT	Function		E	Exponer			1	Mantisso	a		YES
		Default Value					able					
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
		Function					tissa					
		Default Value				Vari	able					
		Sets the voltage lev range is 0.05 to 2V.	el for a	n outpu	it under	voltage	fault. E	xponen	t is fixed	d at -14.	Allowed	
		Format		L	.inear, tv	<i>w</i> o's cor	npleme	nt bina	γ.			
		Bit Position	15	14	13	12	11	10	9	8		
		Access	r	r	r	r	r	r/w	r/w	r/w		
44	VOUT UV FAULT LIMIT	Function		E	Exponer	nt		1	Mantisso	a		YES
		Default Value				Vari	able					
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
		Function				Man	tissa					
		Default Value				Vari	able					
		lasta de la contra	ا		a.a. 4 - 4	lia in in				بالمربق الم		
		Instructs the modu	ie on wł	nat actio					itput un	laervolt	uge tault	
		Format Bit Desition	~	6		Jnsigne			1	0		
45		Bit Position	7	6	5	4	3	2	1	0		
45	VOUT_UV_FAULT_RESPONSE	Access	r/w	r/w	r/w	r/w	r/w	r	r	r		YES
		Function	RSP [1]	RSP [0]	RS[2]	RS[1]	RS[0]	Х	Х	Х		
		Default Value	1	0	1	1	1	0	0	0		
		Sets the current lev maximum of 140A).					ult (car	only be	e lowere	ed belov	v the	
								nt birt			1	
		Format Bit Desition	1 -		inear, tv				/	0		
		Bit Position	15	14	13	12	11	10	9	8		
1.5		Access	r	r	r	r	r	r	r/w	r/w		
46	IOUT_OC_FAULT_LIMIT	Function	1		Exponer		0		Mantisso			YES
		Default Value	1	1	1	1	0	0	1	0		
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
		Function			4	1	tissa		<u> </u>	<u> </u>		
		Default Value	1	1	1	0	0	1	0	0		

7Vdc –14Vdc input; 0.4Vdc to 1.5Vdc output; 120A Output Current

Hex												Non-Volatile
Code	Command				Brief	Descri	ption					Memory Storage
		Sets the value of cu	urrent le	vel at w	hich th	e modu	le aener	rates wo	arnina f	or overc	urrent.	
		Allowed range is 0	to 140A	. The ex	ponent	is fixed	at -2.		5			
		Format						nt binar	'y			
		Bit Position	15	14	13	12	11	10	9	8		
		Access	r	r	r	r	r	r	r	r/w		
4A	IOUT_OC_WARN_LIMIT	Function		E	Exponer	nt			Mantisso			YES
		Default Value	1	1	1	1	0	0	1	0		
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
		Function Default Value	1	0	1	Mun 0	tissa 1	0	0	0		
					1	-			-			
		Sets the temperatu				ver-tem	peratur	re fault o	occurs.	Allowed	range is 35	
		to 140°C. The expo	nent is								1	
		Format						ent binar				
		Bit Position	15	14	13	12	11	10 r/w	9	8		
<u> </u>		Access Function	r	r	r Exponer	r	r		r Mantisso	r		
4F	OT_FAULT_LIMIT	Default Value	0	0	xponer 0	0	0	0	nantisso 0	0		YES
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
		Function	17.00	17	17.00		tissa	17 00	1,	1,		
		Default Value	1	0	0	0	1	0	1	0		
		Configures the over	- - +	ratura f								
		Configures the over Format	r tempe	rature i		Jnsigne	d Pipar					
		Bit Position	7	6	5	4	3	2	1	0		
50	OT FAULT RESPONSE	Access	r/w	r/w	r/w	r/w	r/w	r	r	r		YES
50			RSP	RSP								125
		Function	[1]	[0]	RS[2]	RS[1]	RS[0]	Х	X	Х		
		Default Value	1	0	1	1	1	0	0	0		
		Sets the over temp	oraturo	warnin	n lovol i		owed ro	nnae is '	30 to 13	O°C Th	e evnonent	
		is fixed at 0.	cruture	warning	gievern	I C. All	owcure	unge is .	50 10 13	0 C. III	coponent	
		Format	r –	1	inear t		nnlama	ent binar	<u>.</u>		1	
		Bit Position	15	14	13	12	11	10	9	8		
		Access	r	r	r	r	r	r	r	r		
51	OT_WARN_LIMIT	Function			Exponer		. '		Mantiss		1	YES
		Default Value	0	0	0	0	0	0	0	0	1	
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
		Function					tissa					
		Default Value	0	1	1	1	1	1	0	1		
		Sets the input over	voltaae	fault lin	nit. Exp	onent is	fixed a	t -6. Allo	wed ra	nae is 6	.75 to 15V	
		Format	l					nt binar		.90 10 0]	
		Bit Position	15	14	13	12tr	11	10	y. 9	8	1	
		Access	r	r	r	r	r	r	r/w	r/w	1	
		Function	İ		xponer		•	1	Mantiss		1	1/50
55	VIN_OV_FAULT_LIMIT	Default Value	1	1	0	1	0	0	1	1		YES
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
		Function					tissa					
		Default Value	1	0	1	0	0	0	0	0	J	

7Vdc –14Vdc input; 0.4Vdc to 1.5Vdc output; 120A Output Current

Hex	Command				Brief	,	ntion					Non-Volatile
Code	Command					Descri	ption					Memory Storage
		Configures the VIN	overvol	tage fa								
		Format		r			ed Binary		r	r		
		Bit Position	7	6	5	4	3	2	1	0		
56	VIN_OV_FAULT_RESPONSE	Access	r/w	r/w	r/w	r/w	r/w	r	r	r		YES
		Function	RSP	RSP	RS[2]	RS[1]	RS[0]	х	Х	Х		
		Default Value	[1]	[0] 0	0	0	0	0	0	0		
		Sets the value of th					-	-		-	a ant fived	
		at -6. Allowed range				iuses inț	Jui voili	ige iow	wurnin	y. Expo	lient lixeu	
		Format				NO'S COL	mpleme	nt hina	Ω.		1	
		Bit Position	15	14	13	12	11	10	9	8		
		Access	r	r	r	r	r	r	r/w	r/w		
57	VIN OV WARN LIMIT	Function			Exponer				Mantiss			YES
0.1		Default Value	1	1	0	1	0	0	1	1		. 20
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w	1	
		Function				Man	itissa					
		Default Value	1	0	0	0	0	0	0	0	J	
<u> </u>		Sets the value of th	e input	voltage	that ca	iuses int	out volto	age low	warnin	g. Expoi	nent fixed	
		at -6. Allowed range	e is 5 to	14V.				•		• •	_	
		Format					npleme					
		Bit Position	15	14	13	12	11	10	9	8		
		Access	r	r	r	r	r	r	r/w	r/w		
58	VIN_UV_WARN_LIMIT	Function		1	Exponer		-		Mantiss			YES
		Default Value	1	1	0	1	0	0	0	1		
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
		Function	1	<u>^</u>	1		itissa	^	^	_		
		Default Value	1	0	1	0	0	0	0	0]	
		Sets the value of th	e input	voltaae	that ca	iuses an	input u	Indervo	ltage fa	ult. Expo	onent fixed	
		at -6. Allowed range					1.1.1.0			· •		
		Format			inear, t	wo's cor	mpleme	nt bina	У]	
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r	r	r	r	r	r	r/w	r/w		
59	VIN_UV_FAULT_LIMIT	Function			Exponer				Mantiss	a		YES
		Default Value	1	1	0	1	0	0	0	1		
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
		Function		-		1	itissa	-		-		
		Default Value	1	0	1	0	0	0	0	0	J	
		Instructs the modu	le on wł	nat acti					put und	ervolta	ge fault.	
		Format				· · ·	ed Binary					
		Bit Position	7	6	5	4	3	2	1	0		
5A	VIN_UV_FAULT_RESPONSE	Access	r/w	r/w	r/w	r/w	r/w	r	r	r		YES
		Function	RSP	RSP	RS[2]	RS[1]	RS[0]	Х	Х	Х		
		Default Value	[1] 1	[0] 0	1	1	1	0	0	0		
											•	
		Sets the output volt							nıgh. lı	mplied	exponent of	
		-14 per VOUT_MOD	re comn	nana. A	incord	range is	5 U.U9 to	1.65V.	n /		1	
		Format Bit Position	15	14	linear, tv 13	No s cor 12	npleme		y 9	8		
		Access	15 r	14 r/w	15 r/w	12 r/w	11 r/w	10 r/w	r/w	8 r/w		
5E	POWER GOOD ON	Function	1	17 VV	17 VV		itissa	1 / VV	17 VV	17 VV		YES
JĽ	FOWER_GOOD_ON	Default Value					iable					TLJ
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
		Function	., ••	., ••	., ••		itissa	., ••	., ••	., ••		
		Default Value					iable					
L											J	l

7Vdc –14Vdc input; 0.4Vdc to 1.5Vdc output; 120A Output Current

Code Memory Stor Sets the output voltage level at which the PGOOD plu is de-asserted low. Implied exponent of -14 per VOLT_MODE command. Allowed range is 0.06 to 1.53V. Memory Stor Format Linepr.twois complement binary Bit Position 15 14 13 12 11 10 9 B 5F POWER_GOOD_OFF Format Linepr.twois complement binary West risk VES 60 TON_DELAV Sets the delay time in ms of the output voltage during startup. Allowed range is 0 to 1000ms. Format VES 60 TON_DELAV Sets the delay time in ms of the output voltage during startup. Allowed range is 0 to 1000ms. VES 61 TON_DELAV Sets the in ms of the output voltage during startup. The exponent is fixed at 0. Allowed range is 10 is 1000ms. VES 61 TON_RISE Format Lineor, twois complement binary West VES 61 TON_RISE Sets the inter ms of the output voltage during startup. The exponent is fixed at 0. Allowed range is 10 is 1000ms. VES 61 TON_RISE Format Lineor, twois complement binary VES 8it Position 7	Hex	Command				4 (COI		,					Non-Volatile
SF POWER_GOOD_OFF	Code	communu											Memory Storage
F POWER_GOOD_OFF Format Linear, two's complement binary Wester 5F POWER_GOOD_OFF Bit Position 15 14 13 12 10 9 8 60 TON_DELAY Sets the delay time in ms of the output voltage during startup. Allowed range is 0 to 1000ms. Format Vision										rted low	<i>i</i> . Implied	exponent of	
SF POWER_GOOD_OFF Bit Position 13 14 13 12 11 10 9 8 5F POWER_GOOD_OFF Immunolity Immunolity Montisso				E comr								1	
SF POWER_GOOD_OFF Access Function r r/w r/w <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td>· ·</td> <td></td> <td></td> <td></td> <td>-</td> <td></td>								· ·				-	
SF POWER_GOOD_OFF Function Marting Marting Marting Marting Marting VES 60 TON_DELAY Sets the delay time in ms of the output voltage during startup. Allowed range is 0 to 1000ms. Format Format Linear, two's complement binary Bit Position 7 6 5 4 3 2 1 0										-	-	-	
Bit Position Default Value Variable Bit Position 7 6 5 4 3 2 1 0 Function Function Montisso Montisso Function Montisso Function 60 TON_DELAY Sets the delay time in ms of the output voltage during startup. Allowed range is 0 to 1000ms. Format Innear, two is complement binary Montisso YES 60 TON_DELAY Sets the delay time in ms of the output voltage during startup. Allowed range is 0 to 1000ms. Format Montisso YES 60 TON_DELAY Sets the rise time in ms of the output voltage during startup. The exponent is fixed at 0. Montisso YES 61 TON_RISE Sets the rise time in ms of the output voltage during startup. The exponent is fixed at 0. Allowed range is 1 to 1000ms. YES 61 TON_RISE Format Linear, two's complement binary Fibro to 1 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 <td< td=""><td></td><td></td><td></td><td>r</td><td>r/w</td><td>r/w</td><td></td><td></td><td>r/w</td><td>r/w</td><td>r/w</td><td>-</td><td></td></td<>				r	r/w	r/w			r/w	r/w	r/w	-	
60 TON_DELAY Sets the deby time in ms of the output voltage during startup. Allowed range is 0 to 1000ms. YES 60 TON_DELAY Sets the deby time in ms of the output voltage during startup. Allowed range is 0 to 1000ms. YES 61 TON_DELAY Sets the deby time in ms of the output voltage during startup. Allowed range is 0 to 1000ms. YES 61 TON_DELAY Sets the deby time in ms of the output voltage during startup. The exponent is fixed at 0. Allowed range is 1 to 1000ms. YES 61 TON_RISE Sets the deby time in ms of the output voltage during startup. The exponent is fixed at 0. Allowed range is 1 to 1000ms. YES 61 TON_RISE Format Linear, two's complement binary YES 61 TON_RISE Format Linear, two's complement binary YES 61 TON_RISE Format Linear, two's complement binary YES 62 TOFF_DELAY Sets the disc time in ms of the output voltage during turn. The exponent is fixed at 0. Allowed range is 1 to 1000ms. YES 63 TON_RISE Format Linear, two's complement binary YES 64 TOFF_DELAY Sets the dideby time in ms of the output voltage during turn-off. The expone	51	POWER_GOOD_OFF										-	YES
Access r/w r/w<				7		-		1	2	1	0	-	
Image: constraint of the second of					-					1		-	
Employee Variable 60 TON_DELAV Sets the delay time in ms of the output voltage during startup. Allowed range is 0 to 1000ms. Format Linear, two's complement binary Bit Position 15 14 13 12 11 10 9 8 60 TON_DELAV Bit Position 15 14 13 12 11 10 9 8 61 TON_DELAV Bit Position 7 6 5 4 3 2 1 0 Access r /w r/w				17.00	17 W	1700			17.00	17 VV	17W	-	
60 TON_DELAY Sets the delay time in ms of the output voltage during startup. Allowed range is 0 to 1000ms. Format Bit Position 15 14 13 12 11 10 9 8 Access r r r r r r r r r r r r r r r r r r												-	
60 TON_DELAY Format Linear, two's complement binary 60 TON_DELAY Format 13 12 11 10 9 8 60 TON_DELAY Format T r			L										
60 TON_DELAY Bit Position 15 14 13 12 11 10 9 8 60 TON_DELAY Function Exponent Mantissa Mantissa YES 60 TON_DELAY Bit Position 7 6 5 4 3 2 1 0 61 Bit Position 7 6 5 4 3 2 1 0 61 TON_RISE Sets the rise time in ms of the output voltage during startup. The exponent is fixed at 0. Allowed range is 1 to 1000ms. 0				in ms o		•	•	-			range is 0	to 1000ms.	
60 TON_DELAY Access r						Linear, t		omplem	ent bind		-		
60 TON_DELAY Function Exponent Maritisa YES 60 TON_DELAY Function Exponent Maritisa YES 61 TON_RISE Function Tormat Maritisa YES 61 TON_RISE Sets the rise time in ms of the output voltage during startup. The exponent is fixed at 0. Allowed range is 10 1000ms. Sets the rise time in ms of the output voltage during startup. The exponent is fixed at 0. Allowed range is 10 1000ms. YES 61 TON_RISE Sets the rise time in ms of the output voltage during startup. The exponent is fixed at 0. Allowed range is 10 1000ms. YES 61 TON_RISE Function Exponent Martissa 9 Bit Position 7 6 5 4 3 2 1 0 61 TON_RISE Function Exponent Martissa YES YES 64 TOFF_DELAY Sets the delay time in ms of the output voltage during turn-off. The exponent is fixed at 0. Allowed range is 0 to 1000ms. Tormat Linear, two's complement binary Bit Position 15 14 13 12 11 0 9 8					14	13	12	11	10	-			
60 ION_DELAY Defoult Value 0 <td></td> <td></td> <td></td> <td>r</td> <td></td> <td></td> <td></td> <td>r</td> <td>r</td> <td></td> <td></td> <td>4</td> <td></td>				r				r	r			4	
End Default Value 0	60	TON DELAY					1					4	YES
Access r/w r/w <thr> Uset</thr>					-	-		-	-	-	-	-	. 20
Function Mantissa Default Value 0 0 0 1 0 61 TON_RISE Sets the rise time in ms of the output voltage during startup. The exponent is fixed at 0. Allowed range is 1 to 1000ms. Format Linear, two's complement binary. Image: Sets the rise time in ms of the output voltage during startup. The exponent is fixed at 0. Allowed range is 1 to 1000ms. Format Linear, two's complement binary. Image: Sets the rise time in ms of the output voltage during turn. Sets the rise time in ms of the output voltage during turn. Sets the rise time in ms of the output voltage during turn-off. The exponent is fixed at 0. YES 61 TON_RISE Sets the delay time in ms of the output voltage during turn-off. The exponent is fixed at 0. Allowed range is 0 to 1000ms. Image: Sets the delay time in ms of the output voltage during turn-off. The exponent is fixed at 0. Allowed range is 0 to 1000ms. Image: Sets the delay time in ms of the output voltage during turn-off. The exponent is fixed at 0. Allowed range is 0 to 1000ms. Image: Sets the function to the part of the output voltage during turn-off. The exponent is fixed at 0. Allowed range is 0 to 1000ms. YES 64 TOFF_DELAY Sets the full time in ms of the output voltage during turn-off. Exponent is fixed at 0. Allowed range is 0 to 1000ms. Image: Sets the full time in ms of the output voltage during turn-off. Exponent i											-	4	
Default Value 0 0 0 0 1 0 61 TON_RISE Sets the rise time in ms of the output voltage during startup. The exponent is fixed at 0. Allowed range is 1 to 1000ms. Format Linear, two's complement binary. Bit Position 7 6 5 4 3 2 1 0 61 TON_RISE Format Linear, two's complement binary. Bit Position 7 6 5 4 3 2 1 0 61 TON_RISE Default Value 0				r/w	r/w	r/w			r/w	r/w	r/w	-	
61 Ton_RISE 61 Ton_RISE Format Linear, two's complement binary Bit Position 7 6 5 4 3 2 1 0 Access r r R r				0	0	0		1	0	1	<u> </u>	-	
61 TON_RISE Allowed ronge is 1 to 1000ms. Image: transmitted is a second i			Default value	U	0	0	0	U	0		0		
61 TON_RISE Format Linear, two's complement binary Pinction VES 61 TON_RISE Format Exponent Mantissa YES 64 TOFF_DELAY Sets the delay time in ms of the output voltage during turn-off. The exponent is fixed at 0. Allowed range is 0 to 1000ms. Format Linear, two's complement binary Bit Position 15 14 13 11 10 9 8 64 TOFF_DELAY Format Linear, two's complement binary Bit Position 15 14 13 12 11 10 9 8 64 TOFF_DELAY Function Exponent Mantissa YES 64 TOFF_DELAY Format Linear, two's complement binary			Sets the rise time ir	nms of t	the outp	out volto	age duri	ing star	tup. The	expone	ent is fixed	d at 0.	
61 TON_RISE Bit Position 7 6 5 4 3 2 1 0 61 TON_RISE Bit Position 7 6 5 4 3 2 1 0 61 TON_RISE Function Exponent Montissa Montissa Pefault Value 0 <td></td> <td></td> <td>Allowed range is 1</td> <td>to 1000</td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td>-</td> <td></td>			Allowed range is 1	to 1000								-	
61 TON_RISE Access r									ent bind		•		
61 TON_RISE Function Exponent Mantissa YES Default Value 0 0 0 0 0 0 0 0 Bit Position 7 6 5 4 3 2 1 0 Access r/w				7	6		4	3	2		-		
befault Value 0 <				r				r	r				
Bit Position 7 6 5 4 3 2 1 0 Access r/w	61	TON_RISE			1		1						YES
Access r/w r/w <thr> Format</thr>					-			-	-			-	
Function Mantissa Default Value 0 0 0 1 0 1 Bit Position Sets the delay time in ms of the output voltage during turn-off. The exponent is fixed at 0. Allowed range is 0 to 1000ms. Format Linear, two's complement binary Figure 1 Number 2 Number 2 <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td>-</td> <td></td> <td></td> <td>-</td> <td>-</td> <td></td>								-			-	-	
Default Value 0 0 0 0 1 0 1 64 TOFF_DELAY Sets the delay time in ms of the output voltage during turn-off. The exponent is fixed at 0. Allowed range is 0 to 1000ms. Format Linear, two's complement binary Bit Position 15 14 13 12 11 10 9 8 Access r r R r r r r r/w <				r/w	r/w	r/w			r/w	r/w	r/w	-	
64 TOFF_DELAY Sets the delay time in ms of the output voltage during turn-off. The exponent is fixed at 0. Allowed range is 0 to 1000ms. YES 64 TOFF_DELAY Format Linear, two's complement binary Bit Position YES YES 64 TOFF_DELAY Function Exponent Mantissa YES 65 TOFF_F_FALL Sets the foll time in ms of the output voltage during turn-off. Exponent is fixed at 0. Access r / r R r				0	0	0			1	0	1	-	
64 TOFF_DELAY Format Linear, two's complement binary 8 64 TOFF_DELAY Bit Position 15 14 13 12 11 10 9 8 Access r r R r r r/w r/w <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td>-</td> <td></td> <td>-</td> <td></td> <td></td> <td></td>								-		-			
64 TOFF_DELAY Format Linear, two's complement binary 64 TOFF_DELAY Bit Position 15 14 13 12 11 10 9 8 64 TOFF_DELAY Function Exponent Mantissa Mantissa YES 64 TOFF_DELAY Function Exponent Mantissa Mantissa YES 64 TOFF_DELAY Function Function Exponent Mantissa YES 65 TOFF_F_ALL Sets the fall time in ms of the output voltage during turn-off. Exponent is fixed at 0. Allowed range is 0 to 1000ms. Format Linear, two's complement binary Bit Position 15 14 13 12 11 10 9 8 65 TOFF_FALL Format Linear, two's complement binary Bit Position 15 14 13 12 11 10 9 8 65 TOFF_FALL Format Linear, two's complement binary Bit Position 15 14 13 12 11 10						itput vo	ltage dı	uring tu	rn-off. T	he expo	onent is fix	ked at 0.	
64 TOFF_DELAY Bit Position 15 14 13 12 11 10 9 8 64 TOFF_DELAY Function Exponent Mantissa Mantissa YES 64 TOFF_DELAY Function Exponent Mantissa YES 64 TOFF_DELAY Function Exponent Mantissa YES 65 Access r/w r/w r/w r/w r/w r/w r/w 65 TOFF_FALL Sets the fall time in ms of the output voltage during turn-off. Exponent is fixed at 0. Allowed range is 0 to 1000ms. Format Linear, two's complement binary Bit Position 15 14 13 12 11 10 9 8 Access r r R r r r r/w				O TOOO		lineer		molor	ont hir	201		1	
64 TOFF_DELAY Access r r R r				15							0	-	
64 TOFF_DELAY Function Exponent Mantissa YES 64 TOFF_DELAY Function 0										-		-	
Default Value 0 <	6/1			1				1				-	VEC
Bit Position 7 6 5 4 3 2 1 0 Access r/w r/w <thr th="" w<=""> r/w r/w</thr>	04	IUII_DLLAT		0				0	0	1	1	1	I LO
Access r/w r/w <thr> for</thr>					-	-		-	-	-		1	
Function Mantissa Default Value 0 0 0 0 1 0 65 TOFF_FALL Sets the fall time in ms of the output voltage during turn-off. Exponent is fixed at 0. Allowed range is 0 to 1000ms. Sets the fall time in ms of the output voltage during turn-off. Exponent is fixed at 0. Allowed range is 0 to 1000ms. Format Linear, two's complement binary Bit Position 15 14 13 12 11 10 9 8 Access r r R r r r r/w r/w r/w r/w YES 65 TOFF_FALL Default Value 0					-			-			-	1	
Default Value 0 0 0 0 1 0 65 TOFF_FALL Sets the fall time in ms of the output voltage during turn-off. Exponent is fixed at 0. Allowed range is 0 to 1000ms. Sets the fall time in ms of the output voltage during turn-off. Exponent is fixed at 0. Allowed range is 0 to 1000ms. Sets the fall time in ms of the output voltage during turn-off. Exponent is fixed at 0. Allowed range is 0 to 1000ms. Sets the fall time in ms of the output voltage during turn-off. Exponent is fixed at 0. Allowed range is 0 to 1000ms. Sets the fall time in ms of the output voltage during turn-off. Exponent is fixed at 0. Allowed range is 0 to 1000ms. Sets the fall time in ms of the output voltage during turn-off. Exponent binary Sets the fall time in ms of the output voltage during turn-off. Exponent binary 65 TOFF_FALL Format Linear, two's complement binary Sets the fall time in ms of the output voltage during turn-off. Exponent time binary Sets the fall time in ms of the output voltage during turn-off. Exponent time binary Sets the fall time in ms of the output voltage during turn-off. Exponent time binary Sets the fall time in ms of the output voltage during turn-off. Exponent time binary Sets the fall time in ms of the output voltage during turn-off. Exponent time binary Sets the fall time in ms of the output voltage during turn-off. Exponent time binary Sets the fall time in ms of the output voltage during turn-off. Exponent time binary Sets the fall time in ms of the output voltage during turn-off. Sets during turn-off. Sets				., ••	., ••	., ••			., ••	., ••	., ••	1	
65 TOFF_FALL Format Linear, two's complement binary 65 TOFF_FALL Bit Position 15 14 13 12 11 10 9 8 Access r r R r r r r/w r/w Default Value 0 0 0 0 0 0 0 0 Bit Position 7 6 5 4 3 2 1 0 Access r/w r/w r/w r/w r/w r/w r/w r/w r/w				0	0	0			0	1	0]	
65 TOFF_FALL Format Linear, two's complement binary 65 TOFF_FALL Bit Position 15 14 13 12 11 10 9 8 Access r r R r r r r/w r/w Default Value 0 0 0 0 0 0 0 0 Bit Position 7 6 5 4 3 2 1 0 Access r/w r/w r/w r/w r/w r/w r/w r/w r/w			Sets the fall time in	ms of t	he outo	ut volta	ae durii	na turn-	off Evo	ionent ia	s fixed at () Allowed	
Format Linear, two's complement binary Bit Position 15 14 13 12 11 10 9 8 Access r r R r r r r r r r Wantissa YES 65 TOFF_FALL Default Value 0 0 0 0 0 0 0 0 0 YES 65 TOFF_FALL Bit Position 7 6 5 4 3 2 1 0 0 Access r/w r					ne outp		yc uurli	ig turn-	ο Γνη	onent is			
65 TOFF_FALL Bit Position 15 14 13 12 11 10 9 8 65 TOFF_FALL Access r r R r r r r/w r/w r/w 65 TOFF_FALL Function Exponent Mantissa YES 65 Access r/w r/w r/w r/w r/w r/w YES 65 Access r/w r/w r/w r/w r/w r/w r/w YES						Linear †	two's co	mplem	ent bind	arv		1	
Access r r R r r r r/w r/w 65 TOFF_FALL Function Exponent Mantissa YES Default Value 0 0 0 0 0 0 0 0 YES Bit Position 7 6 5 4 3 2 1 0 Access r/w r/w r/w r/w r/w r/w r/w r/w r/w Function Mantissa Mantissa Mantissa Mantissa Mantissa Mantissa				15	1				1		8	1	
65 TOFF_FALL Function Exponent Mantissa YES Default Value 0 </td <td></td> <td>-</td> <td>1</td> <td></td>											-	1	
Default Value 0 <	65	TOFF_FALL			E		it	•				1	YES
Accessr/wr/wr/wr/wr/wFunctionMantissa		-		0	1		1	0	0	0	0]	
Function Mantissa			Bit Position	7		5				1	-		
				r/w	r/w	r/w			r/w	r/w	r/w		
							1	1					
			Default Value	0	0	0	0	0	1	0	1		

7Vdc –14Vdc input; 0.4Vdc to 1.5Vdc output; 120A Output Current

Hex	Command		-		•	rief Des										Non-Volatile
Code	Commana															Memory Storag
		Returns one byte o	f inform	ation v	vith a s	summa	ry of th	e mos	st criti	cal m	odu	e fau	ults	_		
		Format Bit Position	7	6	5		nsignec 4			2		1	0	_		
78	STATUS_BYTE	Access	r	r r	R		r r	r c		r	_	r r	r	_		
		Flag	X		_			_			-		OTHE	R		
		Default Value	~	011		_0110	Vario	-	_01	12111	Ŭ		01112			
		Returns two bytes	of inforn	nation	with a					s fault	t/wa	rninç	g cono	ditions		
		Format Bit Position	15	14		13	Jnsigne 12		ary 11		10	9	-	8		
		Access	r	r r		R	r		r		r	r		r		
		Flag	VOUT			NPUT	X		PGOC		X	Х		X		
79	STATUS_WORD	Default Value	0001	1001_				iable	000	D	~	~		~		
		Bit Position	7	6		5	4		3		2	1		0		
		Access	r	r		R	r		r		r	r		r		
		Flag	Х	OFF		OUT_OV		00	VIN I	JV TF	MP	CMI	OT	HER		
		-			•0		-	_00 iable								
		Default Value					var	uule								
		Returns one byte o	f inform	ation v	vith the	e status	s of the	modu	ule's o	utput	volt	age	relate	d fault	ts	
		Format					Unsign		nary							
7.4		Bit Position	7		6		5		4	-+	3	2	1	0		
7A	STATUS_VOUT	Access	1 1													
		Flag	Warn Warn Warn													
		Default Value	wam wam													
		Returns one byte o	f inform	ation v	with the	status	of the	modu	ıle's o	utout	cur	renti	relate	d fault	s	
		Format					gned B			utput	cun	CIICI		araan		
7B		Bit Position	7		6 5	4	5	3		2	1	0				
/ D	STATUS_IOUT	Access	r		r r	r		r		r	r	r				
		Flag	IOUT	00	ХХ		IOUT_		/ARN	Х	Х	Х	_			
		Default Value		. f			/ariable			.l.a./a. iv		مامر				
		Returns one b	yte of Ir		ILION W					ile S If	iput	reidi	lea ta	uits		
		Format					Jnsign									
		Bit Position		7		6		5	-	Ψ.	3	2	1	0		
7C	STATUS_INPUT	Access Flag	VIN O	r V FΔII		r I_OV_V		r _UV_	VIN	-	r X	r X	r X	r X		
		i iug	VIIV_0	•_i A0		RNING		NING		ULT	~	\cap		0		
		Default Value						iable				•				
		Returns one byte o	f inform	ation v	vith the	e status	s of the	modı	ule's te	empe	ratu	re re	lated	faults		
		Format					ned Bir									
7D	STATUS_TEMPERATURE	Bit Position	7	,		6	5	4	3	2	1	0				
,0	STATUS_TENTENATURE	Access	r ot t			r	r	r	r		r	r				
		Flag Default Value	OT_F/	AULI	01_0	VARN	X ariable	Х	Х	Х	Х	Х				
			L			V	unuble									
		Returns one byte o	finform	ation	with the	statur	of the	mod	المزد د	0000		ation	rola+	ad fau	ltc	
		Format					Jnsign				unic	auol	rciut		1113	
		Bit Position	7		6	5	4	3	2		1			0		
7E	STATUS CML	Access	r		r	r	r	r	r		r			r		
, _		Class.	Inva	lid	Invalid	PEC				0+h						
		Flag	Comm	nand	Data	Fail	×	Х	Х	Other	Cor	nin F	uult	Х		
		Default Value					Var	iable	ı							
L																

7Vdc –14Vdc input; 0.4Vdc to 1.5Vdc output; 120A Output Current

Hex Code	Command			l	Brief De	scriptio	on				n-Volatile ory Storage
		Returns the value o	of the ini	out volt	aae app	lied to t	the mod	lule.			
		Format			inear, tv				ry		
		Bit Position	15	14	13	12	11	10	Í 9	8	
		Access	r	r	r	r	r	r	r	r	
		Function		E	xponer	nt			Mantiss	a	
88	READ_VIN	Default Value					able				
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r	r	r	r	r	r	r	r	
		Function				Man	tissa				
		Default Value				Vari	able				
		Returns the value o	of the ou	itout vo	ltaae of	the mo	dule Ex	nonent	is fixed	at -14	
		Format			inear, tv						
		Bit Position	15	14	13	12	11	10	9	8	
		Access	r	r	r	r	r	r	r	r	
a-		Function	<u> </u>	ı .	<u> </u>		tissa	· · ·	· · · ·	· · ·	
8B	READ_VOUT	Default Value					able				
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r	r	r	r	r	r	r	r	
		Function	<u> </u>	ı .	<u> </u>		tissa	· · ·	. <u> </u>	· · ·	
		Default Value Variable									
		Returns the value of	f tho ou	itout cu	rront of	tho mo	dulo				
		Format			inear, tv			nt hina	r.v		
		Bit Position	15	14	13	12	11	10	9	8	
		Access	r	r r	r	r	r	r	r	r	
		Function	1	-	xponer		1		Mantiss	· · ·	
8C	READ_IOUT	Default Value		L	лропсі		able		10111133	u	
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r	r	r	r	r	r	r	r	
		Function					tissa			I .	
		Default Value					able				
		Returns a module f	ET nacl	vaao tor	mperati						
		Format			inear, tv			nt hina	n.		
		Bit Position	15	14	13	12	11	10	9	8	
		Access	15 r	r r	r	r	r	r	9 r	o r	
		Function	1		xponer		1		Mantiss		
8D	READ_TEMPERATURE_1	Default Value			poner		able	I'	1011133	u	
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r	r	r	r	r	r	r	r	
		Function		<u> </u>			tissa	L	<u> </u>	· ·	
		Default Value					able				
		Returns the module PWM controller temperature in °C. Format Linear, two's complement binary									
		Format		L	inear, tv	vo's cor	npleme	nt bina	ry		
		Bit Position	15	14	13	12	11	10	9	8	
		Access	r	r	r	r	r	r	r	r	
8E	DEAD TEMPERATURE 2	Function		E	Exponer				Mantiss	a	
OE	READ_TEMPERATURE_2	Default Value					able				
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r	r	r	r	r	r	r	r	
		Function					tissa				
		Default Value				Vari	able				

7Vdc –14Vdc input; 0.4Vdc to 1.5Vdc output; 120A Output Current

Hex Code	Command				Brief De	scriptic	on					Non-Volatile Memory Storage
coue		Returns the switchi				onverter	. The Fr	equenc	y is in K	ilohertz (and	Themory Storuge
		is read only, consist	ting of t									
		Format Bit Position	15	L 14	inear, tv 13	vo's cor 12	npleme 11	nt binai 10	у 9	8		
		Access	r r	r r	r	12 r	r	r	9 r	o r		
95	READ_FREQUENCY	Function				Inte						
	_ (****	Default Value	0	0	0	0	0	0	0	1		
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r	r	r	r	r	r	r	r		
		Function Default Value	1	0	0	Inte 1	o 0	0	0	0		
		Returns one byte in	dicatina	the m	ndule is	compli	ant to P	MBus S	nec 11			
		Format	arcating	g the m			d Binary		000.1.1			
98	PMBUS_REVISION	Bit Position	7	6	5	4	3	2	1	0		YES
		Access	r	r	r	r	r	r	r	r		
		Default Value	0	0	0	1	0	0	0	1		
		Value used to prog Block.	ram spe	ecific pro	oportior	nal coeff	ficient o	f the PI	D comp	ensatior	I	
		Format				vo's cor	npleme					
		Bit Position	15	14	13	12	11	10	9	8		
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
BO	MFR_SPECIFIC_KP	Function Default Value	L			Inte Vari						YES
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
		Function					eger					
		Default Value				Vari	able					
		Value used to prog	ram spe	ecific int	egral co	pefficien	nt of the	PID cor	npenso	ition Bloc	:k	
		Format					npleme		/			
		Bit Position	15	14	13	12	11	10	9 r/w	8		
		Access Function	r/w	r/w	r/w	r/w Inte	r/w	r/w	r/w	r/w		
B1	MFR_SPECIFIC_KI	Default Value				Vari						YES
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
		Function Default Value				Inte Vari	5					
		Default value				Vari	able					
		Value used to prog	ram spe							nsation		
		Format Bit Desition	1 -				npleme		<i>(</i>			
		Bit Position Access	15 r/w	14 r/w	13 r/w	12 r/w	11 r/w	10 r/w	9 r/w	8 r/w		
		Function	17 VV	17 VV	17 VV		eger	17 VV	17 VV	17.00		
B2	MFR_SPECIFIC_KD	Default Value					able					YES
		Bit Position	7	6	5	4	3	2	1	0		-
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
		Function Default Value					eger able					
		Value used to prog	ram spe	ecific alp	oha valu	ie of the	e PID co	mpenso	ation blo	ock		
		Format		L	inear. tv	vo's cor	npleme	nt bina	ŷ			
		Bit Position	15	14	13	12	11	10	9	8		
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
B3	MFR_SPECIFIC_ALPHA	Function					eger					YES
		Default Value Bit Position	7	6	5	Vari 4	able 3	2	1	0		
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
		Function				Inte	eger					
		Default Value					able					

7Vdc –14Vdc input; 0.4Vdc to 1.5Vdc output; 120A Output Current

Hex Code	Command					scriptio	on					Non-Volatile Memory Storage	
ooue		Returns module na	me info	rmation	Iroad	volu)						Themory otorage	
		Format		mutior			d Binar	4					
		Bit Position	15	14	13	12	11	10	9	8			
		Access	r	r	r	r	r	r	r	r			
		Function	'				erved	'	'				
DO	MFR_SPECIFIC_00	Default Value	0	0	0	0	0	0	0	0		YES	
		Bit Position	7	6	5	4	3	2	1	0			
		Access	r	r	r	r	r	r	r	r			
		Function		- 1		e Name		I		erved			
		Default Value	0	0	1	1	1	0	0	0			
		Applies an offset to	the REA	AD_VOL	T comr	nand re	sults to	calibra	te out o	ffset erro	ors		
		in module measure	ments o	of the o	utput vo	oltage (b	etween	125m -	V and +	-124mV).			
		Exponent is fixed at	t -14.										
		Format					npleme						
		Bit Position	15	14	13	12	11	10	9	8			
D4	MFR READ VOUT CAL OFFSET	Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w		YES	
04	MFR_READ_VOUT_CAL_OFFSET	Function					tissa					TES	
		Default Value											
		Bit Position	7	6	5	4	3	2	1	0			
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w			
		Function					tissa						
		Default Value		Var	iable bo	ased on	factory	calibra	tion				
D5	MFR_READ_VOUT_CAL_GAIN	Applies a gain corre errors in module m divided by 8192 to Format Bit Position Access Function Default Value	easurer	nents o te the co 14 r/w	f the ou prrectio inear, tw 13 r/w	tput vol n factor vo's cor 12 r/w Inte	tage. Th	nt bina 10 r/w	oer in th ry 9 r/w	ate out go nis registe 8 r/w	ain er is	YES	
		Bit Position	7	6	5	4	3	2	1	0			
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w			
		Function					eger						
		Default Value		Var	iable bo	ased on	factory	calibra	tion				
D7	MFR_VOUT_CAL_OFFSET	Applies an offset to module output volt Exponent is fixed at Format Bit Position Access Function Default Value	age (be	tween - L 14 r/w	63mV a inear, tv 13 r/w	nd +62r vo's cor 12 r/w Man	ge to co mV) whe npleme 11 r/w tissa factory	en using nt bina 10 r/w	y Trim re ry 9 r/w	8 r/w	ting	YES	
		Bit Position	7	6	5	4	3	2	1	0			
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w			
		Function	.,	.,	1/ **		tissa	.,	1, 17	1, 11			
		Default Value		Var	iable bo		factory	calibra	tion				

7Vdc –14Vdc input; 0.4Vdc to 1.5Vdc output; 120A Output Current

Hex	Command			<u>,</u>	Rrief	Descri	ntion					Non-Volatile
Code	Communu											Memory Storage
D8	MFR_VOUT_SET_MODE	Bit 7 used to deterr Bit 7: 1 – Output vo using the VOUT_TR Bit 7: 0 – Output vo value using the VOI Bit 0: Used to indica levels, margin level more of the values used.	Itage is s IM comn Itage is s UT_TRIM ate whet s or OV/I	olely set nand olely set comma her char JV fault/	t by RTi t by VO Ind. nges ha 'warnir	rim valu oUT_COI ave bee ng levels e defaul	ue and MMAN In maa s. A 1 It. If th	d can b ND and de to t in this	be adju I can b he Vou positio	sted from e adjusted t set point n indicate	set value d from set t, PG On/Off es that one or	YES
		Bit Position	7	6	5	4	3	2	1	0)	
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/\	N	
		Flag	VOUT_S T_MOD		Х	Х	Х	х	Х	USER_CH	HANGES	
		Default Value	1	0	0	0	0	0	0	0)	
		Value used to prog Format Bit Position Access	ram the 15 r/w			on. This vo's con 12 r/w		nent bi 1(nary) (only. 9 8 'w r/w		
		Function	1700	17.00		ger – Mo			• 17	1/00		
DB	MFR_FW_REVISION	Default Value				Vario						
		Bit Position	7	6	5	4	3	2		1 0		
		Access	r/w	r/w	r/w	r/w	r/w		v r/	′w r/w		
		Function			Integ	ger – Mi		ersion				
		Default Value				Vario	able					
DD	MFR_RTUNE_INDEX	Returns the index of is from 0 to 59. Format Bit Position Access Function Default Value	7 r	6 r		Jnsigne 4 r Inte	d Bind 3 r			1 0 r r		YES
		Gets or sets the wr									bit is set, the	
		corresponding PME Format	sus comr	mand is	write p	orotecte Unsig			nly be	read.		
		Bit Position	15	14	13	12		11	10	9	8	
		Access	r	r	r	r		r	r	r	r	
		Function				Re	eserve	ed		·		
		Default Value	х	Х	Х	Х		х	Х	х	х	
DF	MFR_WRITE_PROTECT	Bit Position	7	6	5	4		3	2	1	0	YES
		Access	r	r Roce	r	r		r/w	r/w	r/w	r/w	
		Function Default Value	×	Kese X	erved x	×		1	1	sed 1	0	
		Bit 0: ON_OFF_CON Bit 1: IOUT_OC_FAL Bit 2: OT_FAULT_LII Bit 3: OT_FAULT_RE Bits 4 – 15: Reserve	IFIG JLT_LIMI MIT SP	1	<u> </u>	×		1	1		U	
FO	MFR_MODULE_DATE_LOC _SN	Read only commar YY : year of manufc FF: Factory where r WW: Fiscal week of XXXXXX: Unique nu of the unit.	icture nanufac ⁻ the yea	tured r when ι	unit wa	s manu	ıfactu	red				YES

7Vdc –14Vdc input; 0.4Vdc to 1.5Vdc output; 120A Output Current

Thermal Considerations

GF

Power modules operate in a variety of thermal environments; however, sufficient cooling should always be provided to help ensure reliable operation.

Considerations include ambient temperature, airflow, module power dissipation, and the need for increased reliability. A reduction in the operating temperature of the module will result in an increase in reliability. The thermal data presented here is based on physical measurements taken in a wind tunnel. The test set-up is shown in Figure 37. The preferred airflow direction for the module is in Figure 38.



Figure 37. Thermal Test Setup.



Figure 38. Preferred airflow direction and location of hotspots of the module (Tref).

The thermal reference points, T_{ref} used in the specifications are also shown in Figure 38. For reliable operation the temperatures at these points should not exceed 120°C. The output power of the module should not exceed the rated power of the module (Vo,set x Io,max).

Please refer to the Application Note "Thermal Characterization Process For Open-Frame Board-Mounted Power Modules" for a detailed discussion of thermal aspects including maximum device temperatures.

120A TeraDLynx™: Non-Isolated DC-DC Power Modules

7Vdc -14Vdc input; 0.4Vdc to 1.5Vdc output; 120A Output Current

Example Application Circuit

Requirements:	
Vin:	12V
Vout:	1.2V
lout:	120A max., worst case load transient is from 60A to 90A
ΔVout:	25mV for worst case load transient
Vin, ripple	2% of Vin (240mV p-p)



CI1	$4 \times 0.047 \ \mu\text{F}$ (high-frequency decoupling capacitor)
CI2	12 x 22 µF
CI3	$4 \times 470 \ \mu\text{F}$ (polymer or electrolytic)
CO1	$4 \times 0.047 \ \mu\text{F}$ (high-frequency decoupling capacitor)
CO2	12 x 47 μF, TBD
CO3	10 × 1000 μF, TBD
RTune	3105Ω, TBD
RTrim	5.9ΚΩ
RTrim	5.9ΚΩ

<u>Note:</u> The DATA, CLK and SMBALRT pins do not have any pull-up resistors inside the module. Typically, the PMBus master controller will have pull-up resistors as well as provide the driving source for these signals.

120A TeraDLynx™: Non-Isolated DC-DC Power Modules

4.5Vdc -14Vdc input; 0.4Vdc to 1.5Vdc output; 120A Output Current

Mechanical Outline (SMT)

Dimensions are in millimeters and (inches).

Tolerances: x.x mm \pm 0.5 mm (x.xx in. \pm 0.02 in.) [unless otherwise indicated]

x.xx mm \pm 0.25 mm (x.xxx in \pm 0.010 in.)







FRONT VIEW

SIDE VIEW



BOTTOM VIEW

7Vdc -14Vdc input; 0.4Vdc to 1.5Vdc output; 120A Output Current

Recommended SMT Pad Layout



PIN	FUNCTION	PIN	FUNCTION	PIN	FUNCTION
1	VOUT	15	PWR_GOOD	29	VIN
2	VOUT	16	RTUNE	30	N/A
3	GND	17	TRIM	31	SHARE
4	VOUT	18	SEQ	32	ON/OFF
5	VOUT	19	SIG_GND	33	SMBALERT#
6	GND	20	VS+	34	DATA
7	VOUT	21	VS-	35	CLK
8	VOUT	22	GND	36	ADDR0
9	GND	23	VIN	37	ADDR1
10	VOUT	24	GND	38	GND
11	VOUT	25	VIN		
12	GND	26	GND		
13	GND	27	VIN		
14	SYNC	28	GND		

120A TeraDLynx™: Non-Isolated DC-DC Power Modules

4.5Vdc -14Vdc input; 0.4Vdc to 1.5Vdc output; 120A Output Current

Mechanical Outline (Through hole)

Dimensions are in millimeters and (inches).

Tolerances: x.x mm \pm 0.5 mm (x.xx in. \pm 0.02 in.) [unless otherwise indicated] x.xx mm \pm 0.25 mm (x.xxx in \pm 0.010 in.)





BOTTOM VIEW

7Vdc –14Vdc input; 0.4Vdc to 1.5Vdc output; 120A Output Current



Recommended Through-hole Layout

Note: In the Through-Hole version of the TJT120, pins 1-13, 22-29 and 38 are Through-Hole pins, pins 14-21, 30-37 are SMT pins. The drawing above shows the recommended layout as a combination of holes in the PWB to accommodate the Through-Hole pins and pads on the top layer to accommodate the SMT pins.

PIN	FUNCTION	PIN	FUNCTION	PIN	FUNCTION
1	VOUT	15	PWR_GOOD	29	VIN
2	VOUT	16	RTUNE	30	N/A
3	GND	17	TRIM	31	SHARE
4	VOUT	18	SEQ	32	ON/OFF
5	VOUT	19	SIG_GND	33	SMBALERT#
6	GND	20	VS+	34	DATA
7	VOUT	VOUT 21 VS-		35	CLK
8	VOUT	22	GND	36	ADDR0
9	GND	23	VIN	37	ADDR1
10	VOUT	24	GND	38	GND
11	VOUT	25	VIN		
12	GND	26	GND		
13	GND	27	VIN		
14	SYNC	28	GND		

120A TeraDLynx™: Non-Isolated DC-DC Power Modules

4.5Vdc -14Vdc input; 0.4Vdc to 1.5Vdc output; 120A Output Current

Packaging Details

The 120A TeraDLynx[™] modules are supplied in trays. Modules are shipped in quantities of 12 modules per layer, 24 per box. All Dimensions are in millimeters and (in inches).





120A TeraDLynx™: Non-Isolated DC-DC Power Modules

7Vdc –14Vdc input; 0.4Vdc to 1.5Vdc output; 120A Output Current

Surface Mount Information

Pick and Place

The 120A TeraDLynx[™] modules use an open frame construction and are designed for a fully automated assembly process. The modules are fitted with a label designed to provide a large surface area for pick and place operations. The label meets all the requirements for surface mount processing, as well as safety standards, and is able to withstand reflow temperatures of up to 300°C. The label also carries product information such as product code, serial number and the location of manufacture.

Nozzle Recommendations

The module weight has been kept to a minimum by using open frame construction. Variables such as nozzle size, tip style, vacuum pressure and placement speed should be considered to optimize this process. The minimum recommended inside nozzle diameter for reliable operation is 15mm. The maximum nozzle outer diameter, which will safely fit within the allowable component spacing, is 22 mm.

Bottom Side / First Side Assembly

This module is not recommended for assembly on the bottom side of a customer board. If such an assembly is attempted, components may fall off the module during the second reflow process.

Lead Free Soldering

The modules are lead-free (Pb-free) and RoHS compliant and fully compatible in a Pb-free soldering process. Failure to observe the instructions below may result in the failure of or cause damage to the modules and can adversely affect long-term reliability.

Pb-free Reflow Profile

Power Systems will comply with J-STD-020 Rev. C (Moisture/Reflow Sensitivity Classification for Nonhermetic Solid State Surface Mount Devices) for both Pb-free solder profiles and MSL classification procedures. This standard provides a recommended forced-air-convection reflow profile based on the volume and thickness of the package (table 4-2). The suggested Pb-free solder paste is Sn/Ag/Cu (SAC). The recommended linear reflow profile using Sn/Ag/Cu solder is shown in Fig. 40. Soldering outside of the recommended profile requires testing to verify results and performance.

MSL Rating

The 120A TeraDLynx^{TM} modules have a MSL rating of 3.

Storage and Handling

The recommended storage environment and handling procedures for moisture-sensitive surface mount packages is detailed in J-STD-033 Rev. A (Handling, Packing, Shipping and Use of Moisture/Reflow Sensitive Surface Mount Devices). Moisture barrier bags (MBB) with desiccant are required for MSL ratings of 2 or greater. These sealed packages should not be broken until time of use. Once the original package is broken, the floor life of the product at conditions of \leq 30°C and 60% relative humidity varies according to the MSL rating (see J-STD-033A). The shelf life for dry packed SMT packages will be a minimum of 12 months from the bag seal date, when stored at the following conditions: < 40° C, < 90% relative humidity.



Figure 39. Recommended linear reflow profile using Sn/Ag/Cu solder.

Post Solder Cleaning and Drying Considerations

Post solder cleaning is usually the final circuit-board assembly process prior to electrical board testing. The result of inadequate cleaning and drying can affect both the reliability of a power module and the testability of the finished circuit-board assembly. For guidance on appropriate soldering, cleaning and drying procedures, refer to *Board Mounted Power Modules: Soldering and Cleaning* Application Note (AN04-001).

4.5Vdc –14Vdc input; 0.4Vdc to 1.5Vdc output; 120A Output Current

Ordering Information

Please contact your GE Sales Representative for pricing, availability and optional features.

Table 5. Device Codes

Device Code	Input Voltage Range	Output Voltage	Output Current	On/Off Logic	Interconnect	Comcodes
TJT120A0X3Z	7 – 14Vdc	0.4 – 1.5 Vdc	120A	Negative	TH	150043982
TJT120A0X43Z	7 – 14Vdc	0.4 – 1.5 Vdc	120A	Positive	TH	150049601
TJT120A0X3-SZ	7 – 14Vdc	0.4 – 1.5 Vdc	120A	Negative	SMT	150041745
TJT120A0X43-SZ	7 – 14Vdc	0.4 – 1.5 Vdc	120A	Positive	SMT	150049603

-Z refers to RoHS compliant parts

Table 6. Coding Scheme

Package Identifier	Family	Sequencing Option	Output current		On/Off logic	Remote Sense	Options		ROHS Compliance
Т	J	Т	120A0	x		3	-SR	-Н	Z
P=Pico U=Micro M=Mega G=Giga T=Tera	J = DLynx II	T=with EZ Sequence X=without sequencing	120A	X = programm able output	4 = positive No entry = negative	3 = Remote Sense	S = Surface Mount R = Tape & Reel No entry = Through hole	Extra Ground Pins	Z = ROHS6

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